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Product name	Description	Version
MC-1513-2RE	Datasheet of MC-1513-2RE standalone GPS module	1.3

1 Introduction

LOCOSYS GPS MC-1513-2RE module features high sensitivity, low power and ultra small form factor. This GPS module is powered by MediaTek MT3337E chip which can provide you with superior sensitivity and performance even in urban canyon and dense foliage environment. The miniature size makes the module easy and the best choice to integrate into portable device like mobile phone, PDAs, camera and vehicle locators.

This module supports self-generate orbit prediction, EASY™, to achieve faster cold start and warm start. The EASY™ does not need of both network assistance and host CPU's intervention. The prediction is valid for up to 3 days and updates automatically from time to time when GPS module is powered on and satellites are available.

2 Features

- MediaTek high sensitivity solution
- Support 66-channel GPS
- Ultra low power consumption
- Fast TTFF at low signal level
- Built-in 12 multi-tone active interference canceller
- Built-in DC/DC converter to save power
- Allow direct connection with the lithium battery
- Up to 10 Hz update rate
- ±11ns high accuracy time pulse (1PPS)
- Support 1PPS synchronize with NMEA output
- Supports self-generate orbit prediction to achieve faster cold start
- Support Japan QZSS
- Indoor and outdoor multi-path detection and compensation
- Small form factor 15 x 13 x 2.2 mm
- SMD type with stamp holes; RoHS compliant

3 Application

- Personal positioning and navigation
- Automotive navigation
- Marine navigation

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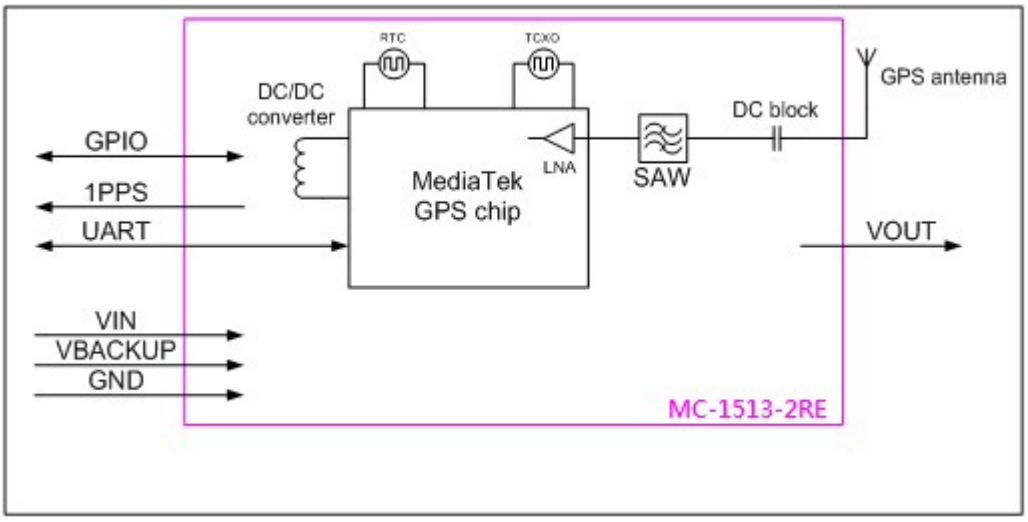

Fig 3-1 System block diagram.

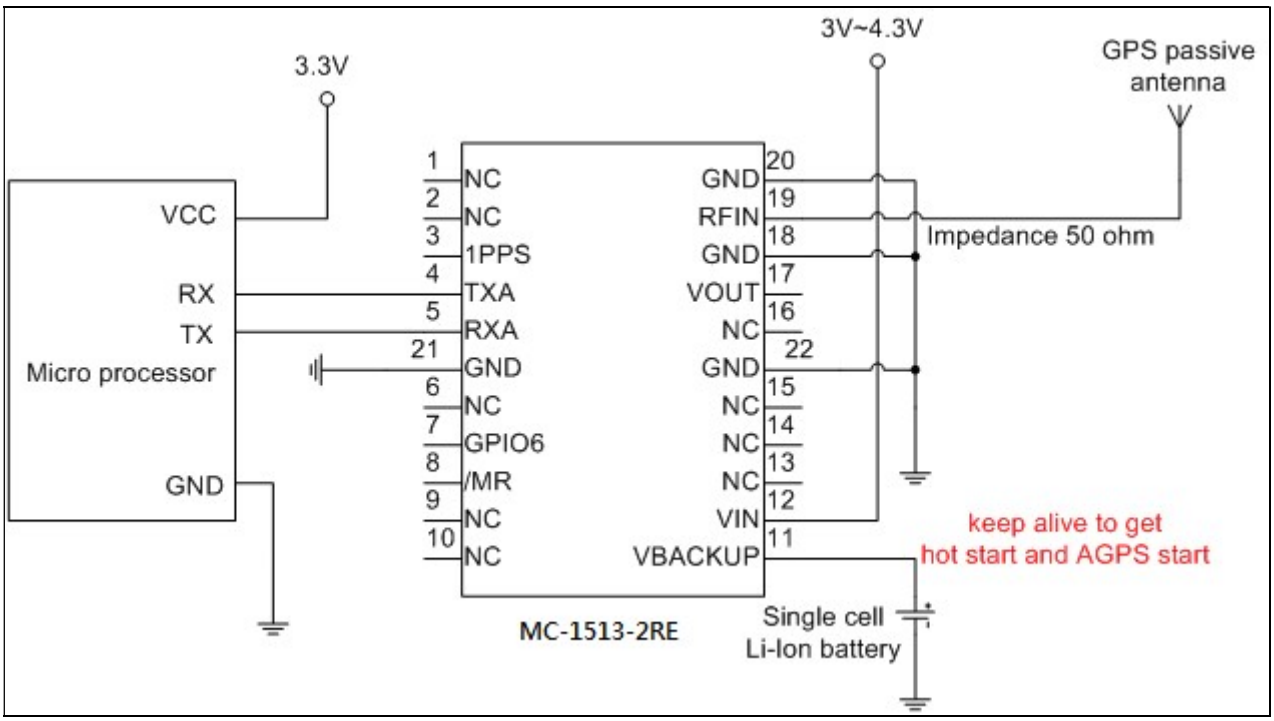

Fig 3-2 Typical application circuit that uses passive antenna.

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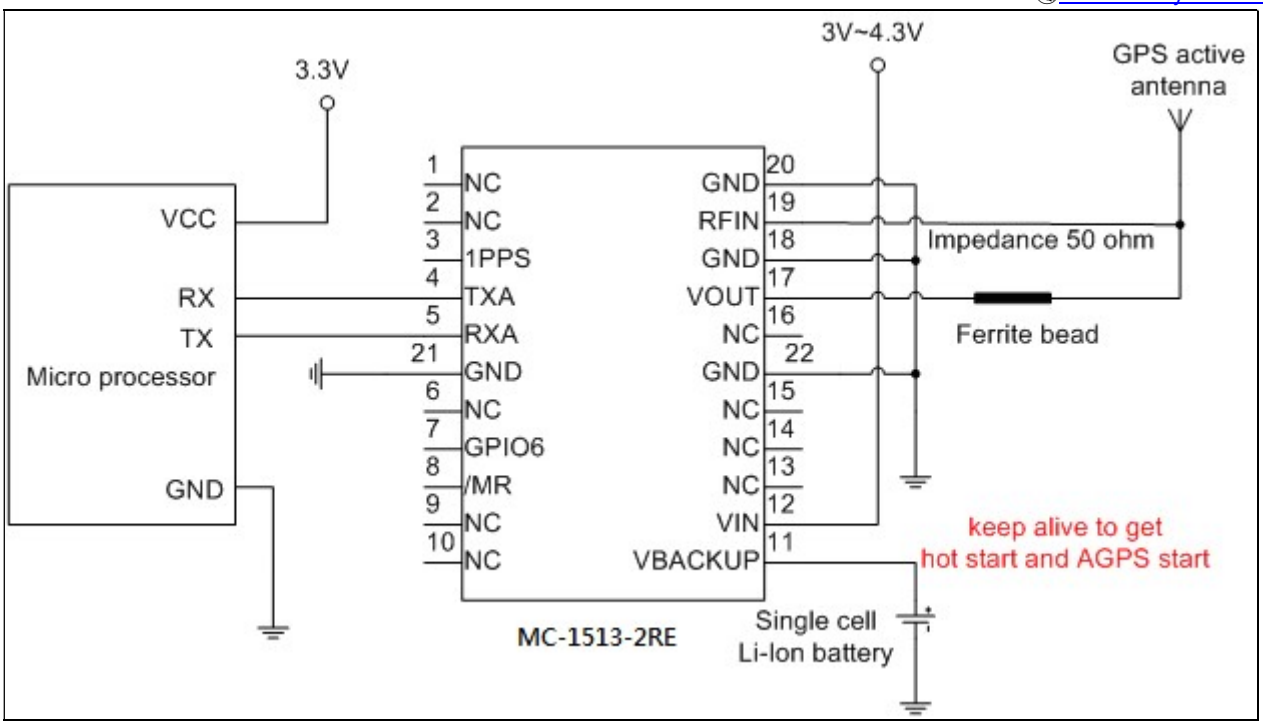

Fig 3-3 Typical application circuit that uses active antenna.

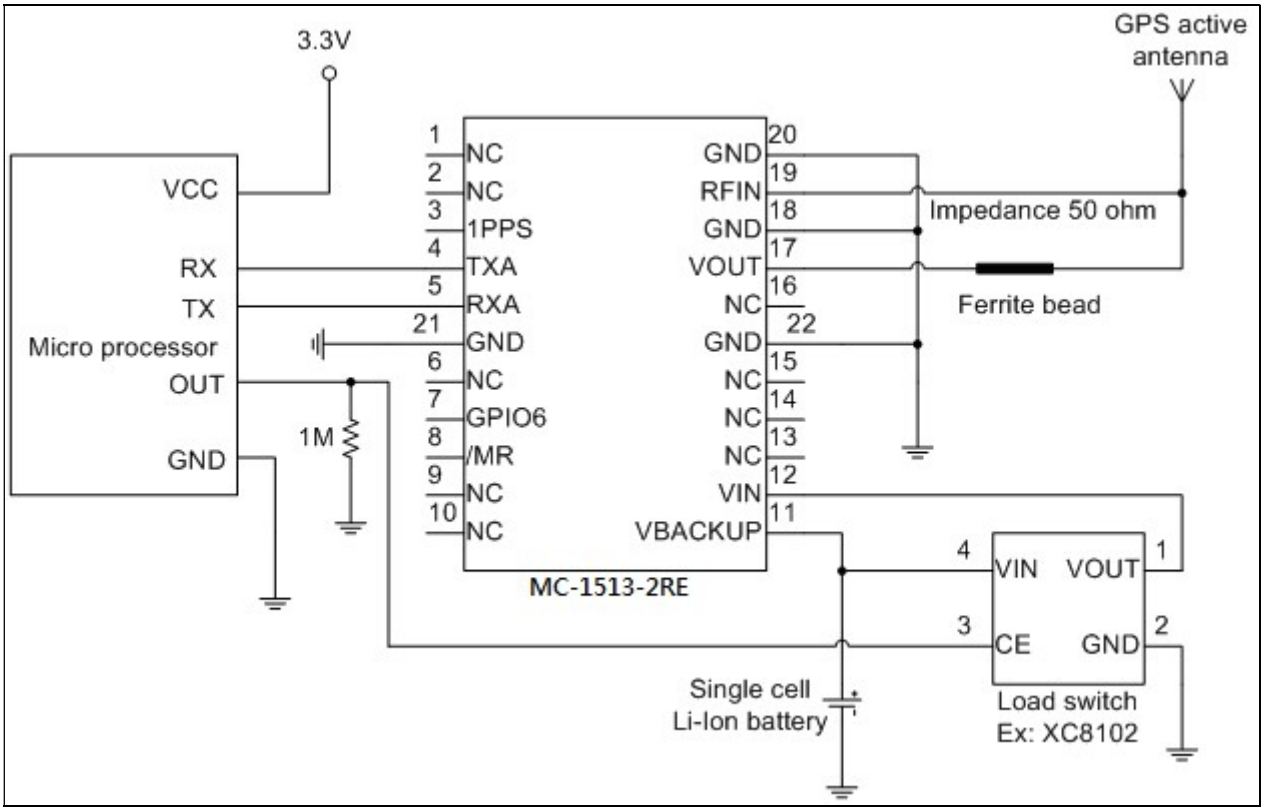

Fig 3-4 Typical application circuit that directly uses a Li-Ion battery as power source to save power.

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4 GPS receiver

Chip	MediaTek MT3337E	
Frequency	L1 1575.42MHz, C/A code	
Channels	Support 66 channels	
Update rate	1Hz default, up to 10Hz	
Sensitivity	Tracking	-161dBm, up to -165dBm (with external LNA)
	Cold start	-143dBm, up to -148dBm (with external LNA)
Acquisition Time	Hot start (Open Sky)	< 1s (typical)
	Hot start (Indoor)	< 30s
	Cold Start (Open Sky)	32s (typical)
		< 15s (typical) with self-generate orbit prediction
Position Accuracy	Autonomous	2.5m CEP
Datum	WGS-84 (default)	
Max. Altitude	< 50,000 m	
Max. Velocity	< 515 m/s	
Protocol Support	NMEA 0183 ver 3.01	9600 bps, 8 data bits, no parity, 1 stop bits (default) 1Hz: GGA, GLL, GSA, GSV, RMC, and VTG

5 Software interface

5.1 NMEA output message

Table 5.1-1 NMEA output message

NMEA record	Description
GGA	Global positioning system fixed data
GLL	Geographic position - latitude/longitude
GSA	GNSS DOP and active satellites
GSV	GNSS satellites in view
RMC	Recommended minimum specific GNSS data
VTG	Course over ground and ground speed

- **GGA--- Global Positioning System Fixed Data**

Table 5.1-2 contains the values for the following example:

$GPGGA,053740.000,2503.6319,N,12136.0099,E,1,08,1.1,63.8,M,15.2,M,,0000*64

Table5.1- 2 GGA Data Format

Name	Example	Units	Description
Message ID	$GPGGA		GGA protocol header
UTC Time	053740.000		hhmmss.sss

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Latitude	2503.6319		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12136.0099		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Position Fix Indicator	1		See Table 5.1-3
Satellites Used	08		Range 0 to 12
HDOP	1.1		Horizontal Dilution of Precision
MSL Altitude	63.8	meters	
Units	M	meters	
Geoid Separation	15.2	meters	
Units	M	meters	
Age of Diff. Corr.		second	Null fields when DGPS is not used
Diff. Ref. Station ID	0000		
Checksum	*64		
<CR> <LF>			End of message termination

Table 5.1-3 Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3-5	Not supported
6	Dead Reckoning Mode, fix valid

● GLL--- Geographic Position – Latitude/Longitude

Table 5.1-4 contains the values for the following example:

$GPGLL,2503.6319,N,12136.0099,E,053740.000,A,A*52

Table 5.1-4 GLL Data Format

Name	**Example**	**Units**	**Description**
Message ID	$GPGLL		GLL protocol header
Latitude	2503.6319		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12136.0099		dddmm.mmmm
E/W indicator	E		E=east or W=west
UTC Time	053740.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Mode	A		A=autonomous, D=DGPS, E=DR, N=Data not valid,

			R=Coarse Position, S=Simulator
Checksum	*52		
<CR> <LF>			End of message termination

● GSA---GNSS DOP and Active Satellites

Table 5.1-5 contains the values for the following example:

$GPGSA,A,3,24,07,17,11,28,08,20,04,,,,,2.0,1.1,1.7*35

Table 5.1-5 GSA Data Format

Name	**Example**	**Units**	**Description**
Message ID	$GPGSA		GSA protocol header
Mode 1	A		See Table 5.1-6
Mode 2	3		See Table 5.1-7
ID of satellite used	24		Sv on Channel 1
ID of satellite used	07		Sv on Channel 2
….			….
ID of satellite used			Sv on Channel 12
PDOP	2.0		Position Dilution of Precision
HDOP	1.1		Horizontal Dilution of Precision
VDOP	1.7		Vertical Dilution of Precision
Checksum	*35		
<CR> <LF>			End of message termination

Table 5.1-6 Mode 1

Value	Description
M	Manual- forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

Table 5.1-7 Mode 2

Value	Description
1	Fix not available
2	2D
3	3D

● GSV---GNSS Satellites in View

Table 5.1-8 contains the values for the following example:

$GPGSV,3,1,12,28,81,285,42,24,67,302,46,31,54,354,,20,51,077,46*73

$GPGSV,3,2,12,17,41,328,45,07,32,315,45,04,31,250,40,11,25,046,41*75

$GPGSV,3,3,12,08,22,214,38,27,08,190,16,19,05,092,33,23,04,127,*7B

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Table 5.1-8 GSV Data Format

Name	Example	Units	Description
Message ID	$GPGSV		GSV protocol header
Total number of messages[1]	3		Range 1 to 4
Message number[1]	1		Range 1 to 4
Satellites in view	12		
Satellite ID	28		Channel 1 (Range 01 to 196)
Elevation	81	degrees	Channel 1 (Range 00 to 90)
Azimuth	285	degrees	Channel 1 (Range 000 to 359)
SNR (C/No)	42	dB-Hz	Channel 1 (Range 00 to 99, null when not tracking)
Satellite ID	20		Channel 4 (Range 01 to 196)
Elevation	51	degrees	Channel 4 (Range 00 to 90)
Azimuth	077	degrees	Channel 4 (Range 000 to 359)
SNR (C/No)	46	dB-Hz	Channel 4 (Range 00 to 99, null when not tracking)
Checksum	*73		
<CR> <LF>			End of message termination

Note 1: Depending on the number of satellites tracked multiple messages of GSV data may be required.

● RMC---Recommended Minimum Specific GNSS Data

Table 5.1-9 contains the values for the following example:

$GPRMC,053740.000,A,2503.6319,N,12136.0099,E,2.69,79.65,100106,,,A*53

Table 5.1-9 RMC Data Format

Name	Example	Units	Description
Message ID	$GPRMC		RMC protocol header
UTC Time	053740.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	2503.6319		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12136.0099		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Speed over ground	2.69	knots	True
Course over ground	79.65	degrees	
Date	100106		ddmmyy
Magnetic variation		degrees	
Variation sense			E=east or W=west (Not shown)
Mode	A		A=autonomous, D=DGPS, E=DR, N=Data not valid, R=Coarse Position, S=Simulator

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Checksum	*53		
<CR> <LF>			End of message termination

- **VTG---Course Over Ground and Ground Speed**

Table 5.1-10 contains the values for the following example:

$GPVTG,79.65,T,,M,2.69,N,5.0,K,A*38

Table 5.1-10 VTG Data Format

Name	**Example**	**Units**	**Description**
Message ID	$GPVTG		VTG protocol header
Course over ground	79.65	degrees	Measured heading
Reference	T		True
Course over ground		degrees	Measured heading
Reference	M		Magnetic
Speed over ground	2.69	knots	Measured speed
Units	N		Knots
Speed over ground	5.0	km/hr	Measured speed
Units	K		Kilometer per hour
Mode	A		A=autonomous, D=DGPS, E=DR, N=Data not valid, R=Coarse Position, S=Simulator
Checksum	*38		
<CR> <LF>			End of message termination

5.2 Proprietary NMEA input/output message

Please refer to MTK proprietary message.

5.3 Examples to configure the power saving mode of GPS module

The GPS module supports power saving mode that user can configure by issuing software commands.

5.3.1 Standby mode

User can issue software command to make GPS module go into standby mode that consumes less than 200uA current. GPS module will be awaked when receiving any byte. The following flow chart is an example to make GPS module go into standby mode and then wake up.

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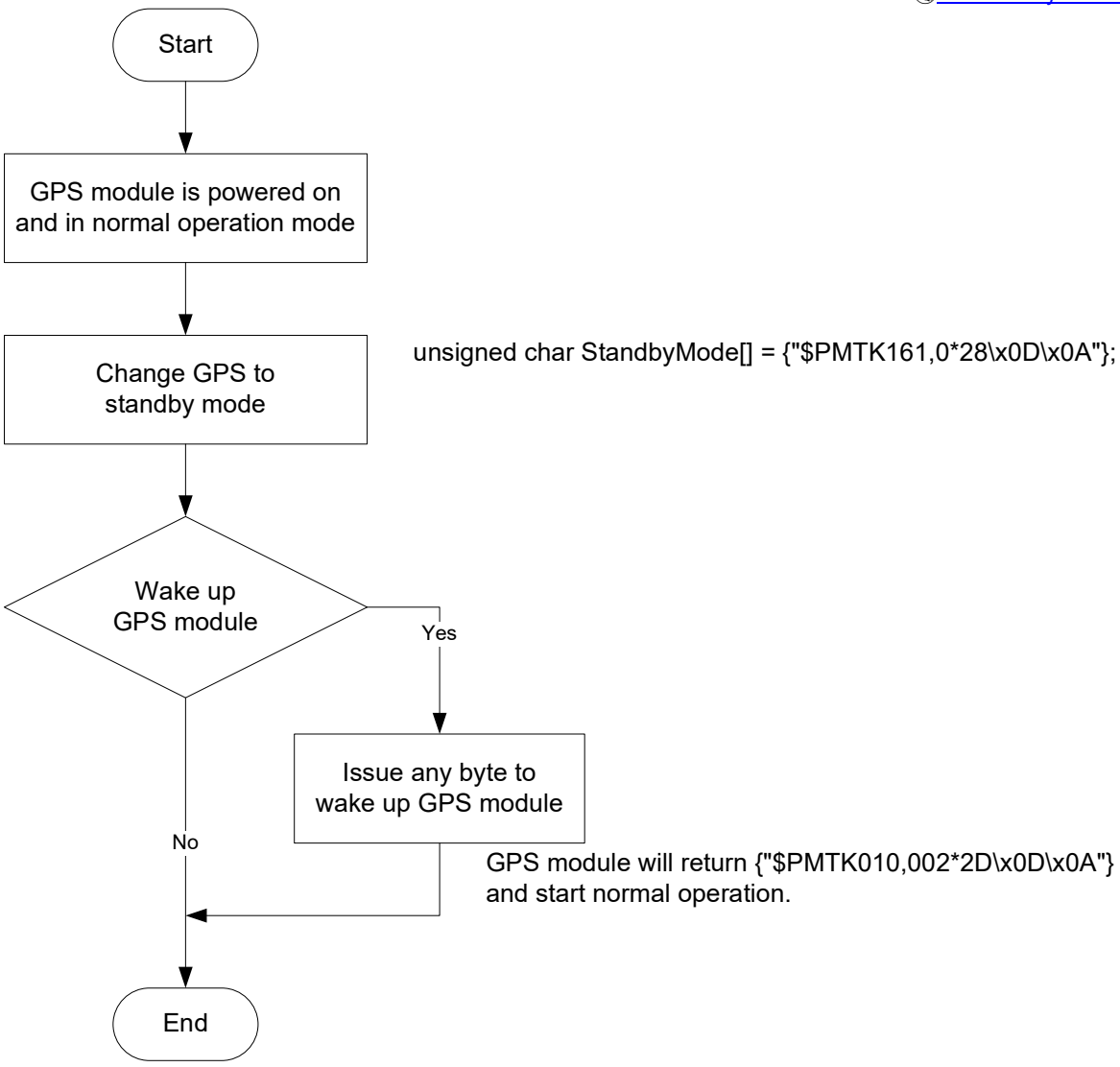

5.4 Examples to configure the update rate of GPS module

The GPS module supports up to 10Hz update rate that user can configure by issuing software commands. Note that the configurations by software commands are stored in the battery-backed SRAM that is powered through VBACKUP pin. Once it drains out, the default/factory settings will be applied.

Due to the transmitting capacity per second of the current baud rate, GPS module has to be changed to higher baud rate for high update rate of position fix. The user can use the following software commands to change baud rate.

Baud rate	Software command
Factory default	$PMTK251,0*28<CR><LF>
4800	$PMTK251,4800*14<CR><LF>
9600	$PMTK251,9600*17<CR><LF>
19200	$PMTK251,19200*22<CR><LF>
38400	$PMTK251,38400*27<CR><LF>

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57600	$PMTK251,57600*2C<CR><LF>
115200	$PMTK251,115200*1F<CR><LF>

Note: <CR> means Carriage Return, i.e. 0x0D in hexadecimal. <LF> means Line Feed, i.e. 0x0A in hexadecimal.

If the user does not want to change baud rate, you can reduce the output NMEA sentences by the following software commands.

NMEA sentence	Software command
Factory default	$PMTK314,-1*04<CR><LF>
Only GLL at 1Hz	$PMTK314,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only RMC at 1Hz	$PMTK314,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only VTG at 1Hz	$PMTK314,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only GGA at 1Hz	$PMTK314,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only GSA at 1Hz	$PMTK314,0,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only GSV at 1Hz	$PMTK314,0,0,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only ZDA at 1Hz	$PMTK314,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,1,0*29<CR><LF>
RMC, GGA, GSA at 1Hz and GSV at 0.2Hz	$PMTK314,0,1,0,1,1,5,0,0,0,0,0,0,0,0,0,0,0,0*2C<CR><LF>
If the command is correct and executed, GPS module will output message $PMTK001,314,3*36<CR><LF>	

After the GPS module is changed to higher baud rate or reduced NMEA sentence, the user can configure it to high update rate of position fix by the following commands.

Interval of position fix	Software command
Every 100ms (10Hz)(1)	$PMTK220,100*2F<CR><LF>
Every 200ms (5Hz)	$PMTK220,200*2C<CR><LF>
Every 500ms (2Hz)	$PMTK220,500*2B<CR><LF>
Every 1000ms (1Hz)	$PMTK220,1000*1F<CR><LF>
Every 2000ms (0.5Hz)(2)	$PMTK220,2000*1C<CR><LF>
If the command is correct and executed, GPS module will output message $PMTK001,220,3*30<CR><LF>	

Note 1: The minimum interval of position fix is 100ms, i.e. the maximum update rate is 10Hz.

Note 2: The current consumption is the same with the update rate of 1Hz.

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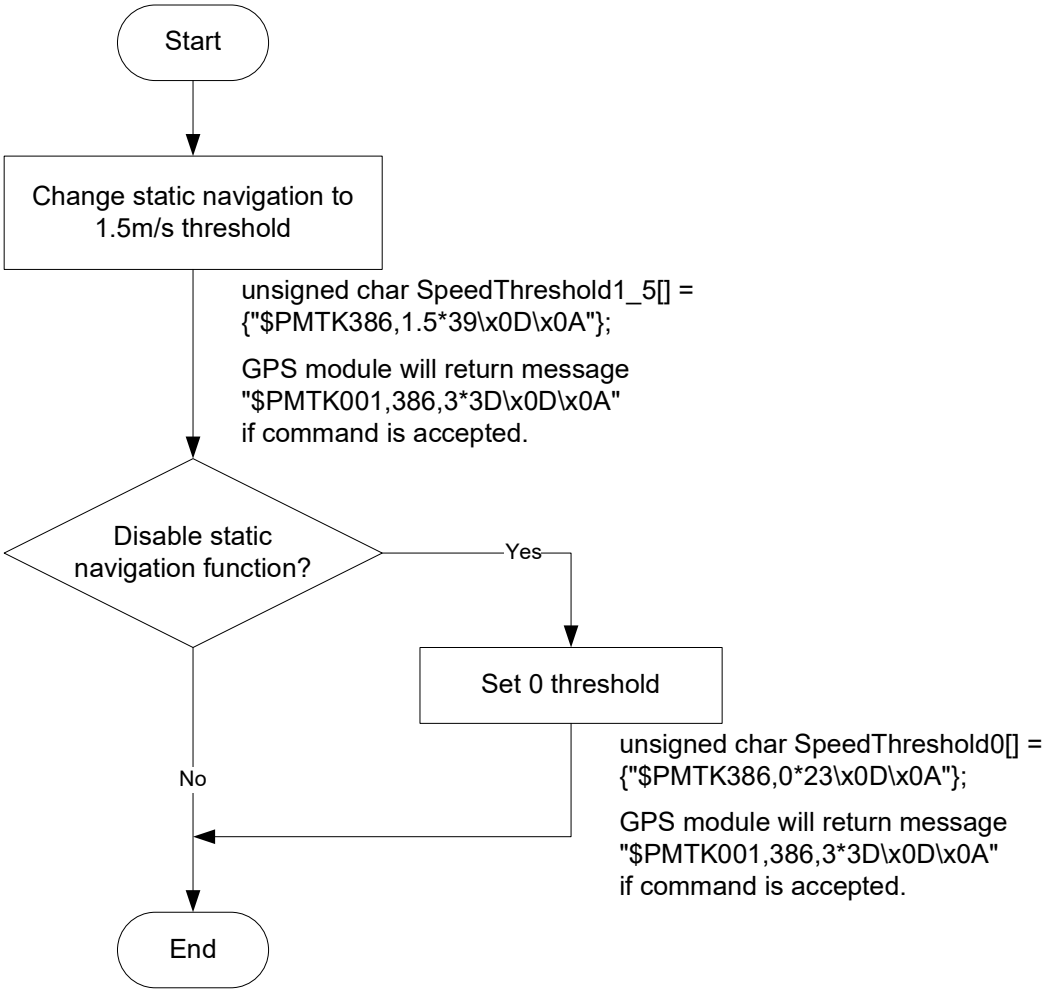
5.5 Configure the static navigation parameter

The output position of GPS module will keep the same and output speed will be zero if the actual speed is below the threshold of the static navigation parameter. This is useful for different applications. For example, the car stopped at a red light will get stationary GPS position if the threshold is 1.5m/s. It is better to disable this function by setting threshold to 0 for pedestrian navigation. This function is default disabled.

The format of the software command is as below.

$PMTK386,speed threshold*checksum<CR><LF>

The unit of speed threshold is meter per second. The range of speed threshold is from 0.1m/s to 2.0m/s. Value 0 is to disable the function.



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6 Pin assignment and descriptions

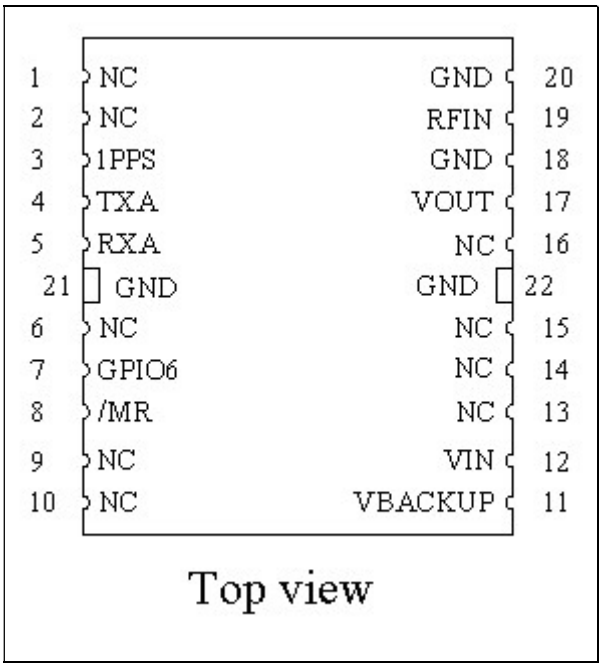

Table 6-1 Pin descriptions

Pin #	Name	Type	Description	Note
1	NC		Not connect	
2	NC		Not connect	
3	1PPS	O	Pulse per second (default 100 ms pulse/sec when 3D fix is available)	
4	TXA	O	Serial output for channel A (Default NMEA)	
5	RXA	I	Serial input for channel A (Default NMEA)	
6	NC		Not connect	
7	GPIO6	O	Default status indicator. When GPS position fix is available, it outputs 100ms high per second, otherwise it outputs low.	
8	/MR	I	Manual reset input pin. Active at “L” input. Internal pulled up via a resistor. If /MR pin is not necessary, open this node.	
9	NC		Not connect	
10	NC		Not connect	
11	VBACKUP	P	Backup battery supply voltage This pin must be powered to enable the module.	
12	VIN	P	DC supply voltage	
13	NC		Not connect	
14	NC		Not connect	

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15	NC		Not connect	
16	NC		Not connect	
17	VOUT	P	Linear regulator power output, 2.8V (Do not use this as power source of backup battery)	
18	GND	P	Ground	
19	RFIN	I	GPS RF signal input	
20	GND	P	Ground	
21	GND	P	Ground	
22	GND	P	Ground	

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7 DC & Temperature characteristics

7.1 Absolute maximum ratings

Parameter	Symbol	Ratings	Units
Input Voltage	VIN	4.3	V
Input Backup Battery Voltage	VBACKUP	4.3	V
2.8V Output Current	Iout	50	mA
Operating Temperature Range	Topr	-40 ~ 85	°C
Storage Temperature Range	Tstg	-40 ~ 85	°C

7.2 DC Electrical characteristics

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Units
Input Voltage	VIN	Iout = 0	3.0		4.3	V
Input Backup Battery Voltage	VBACKUP		2.0		4.3	V
2.8V Output Voltage	VOUT		2.7	2.8	2.9	V
Supply Current	Iss	VIN = 3.3V, Iout = 0, Peak Acquisition Tracking Standby		 14 12(1) 135	44	 mA mA mA uA
Backup Battery Current	Ibat	VIN = 0V		6		uA
2.8V Output Current	Iout	VIN = 3.3V			30	mA
High Level Input Voltage	V_{IH}		2.0		3.6	V
Low Level Input Voltage	V_{IL}		-0.3		0.8	V
High Level Input Current	I_{IH}	no pull-up or down	-1		1	uA
Low Level Input Current	I_{IL}	no pull-up or down	-1		1	uA
High Level Output Voltage	V_{OH}		2.4			V
Low Level Output Voltage	V_{OL}				0.4	V
High Level Output Current	I_{OH}			2		mA
Low Level Output Current	I_{OL}			2		mA
Minimum Pulse Width	T_{MPW}	For /MR pin	1			mS

Note 1. Measured when position fix (1Hz) is available and input voltage is 3.3V. For different input voltage, the current consumption is as below chart. This is because MC-1513-2RE is built-in DC/DC converter.

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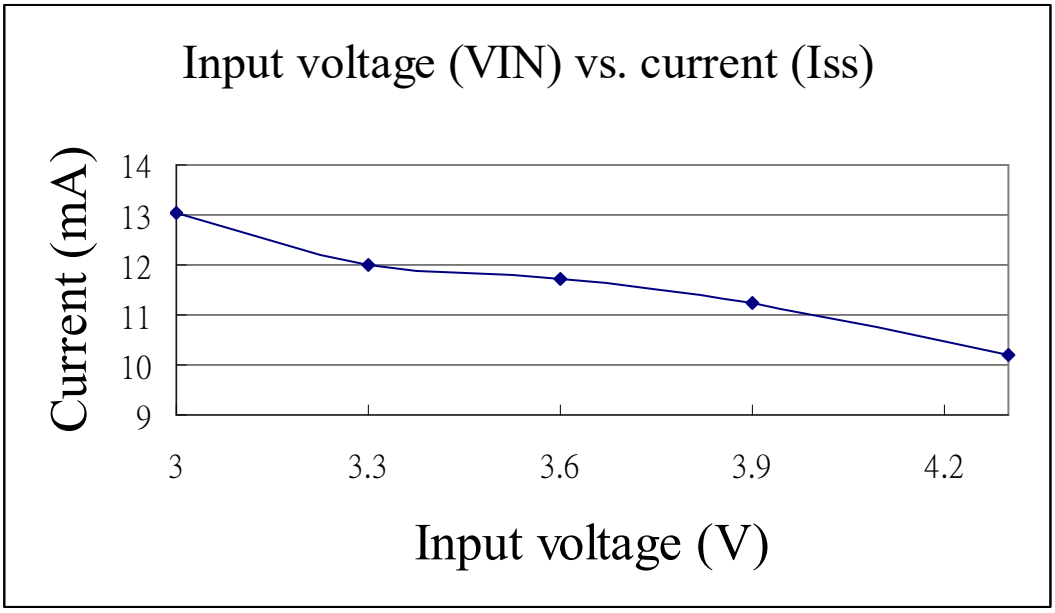

7.3 Temperature characteristics

Parameter	Symbol	Min.	Typ.	Max.	Units
Operating Temperature	Topr	-40	-	85	°C
Storage Temperature	Tstg	-40	25	85	°C

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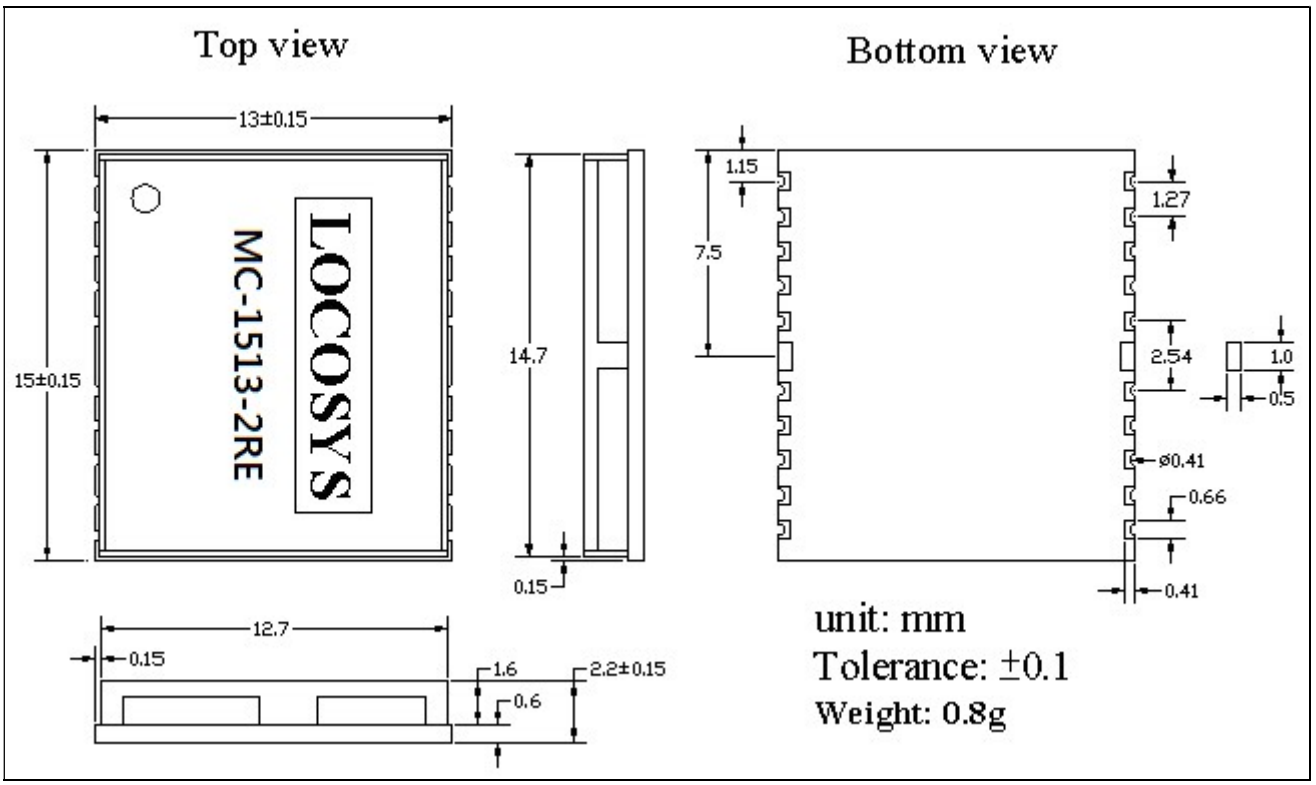
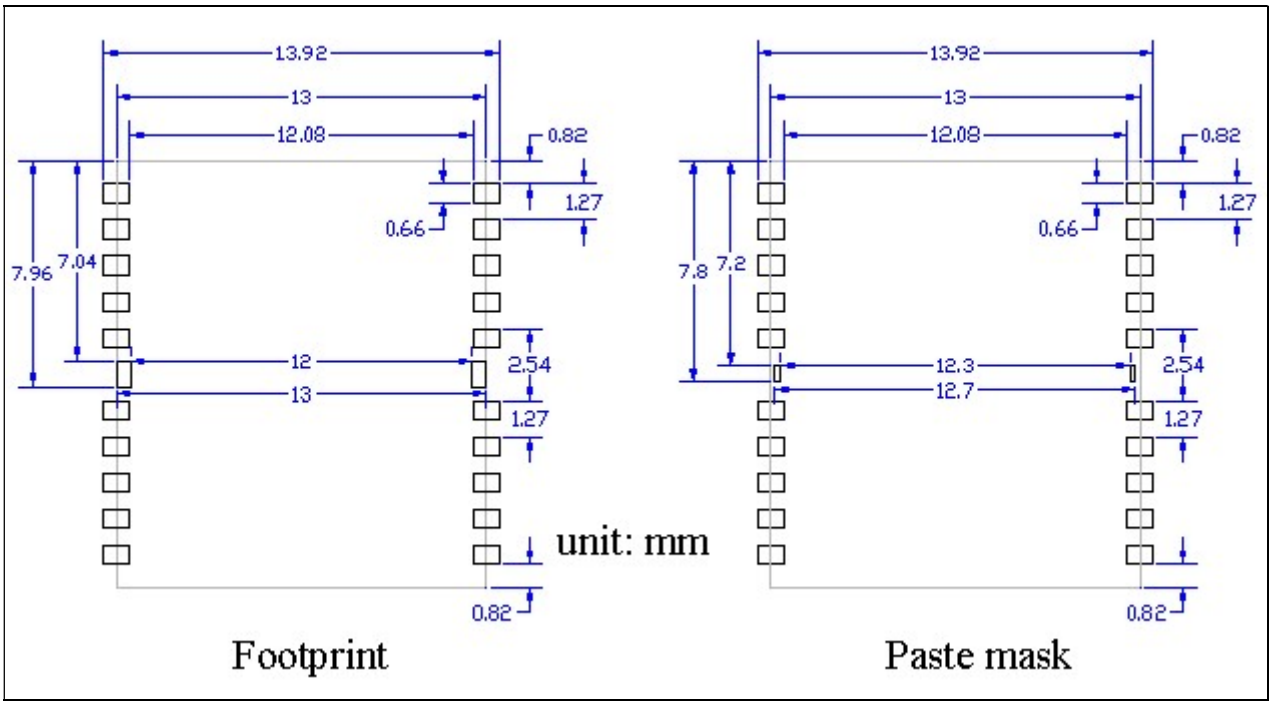
8 Mechanical specification

8.1 Outline dimensions



8.2 Recommended land pattern dimensions



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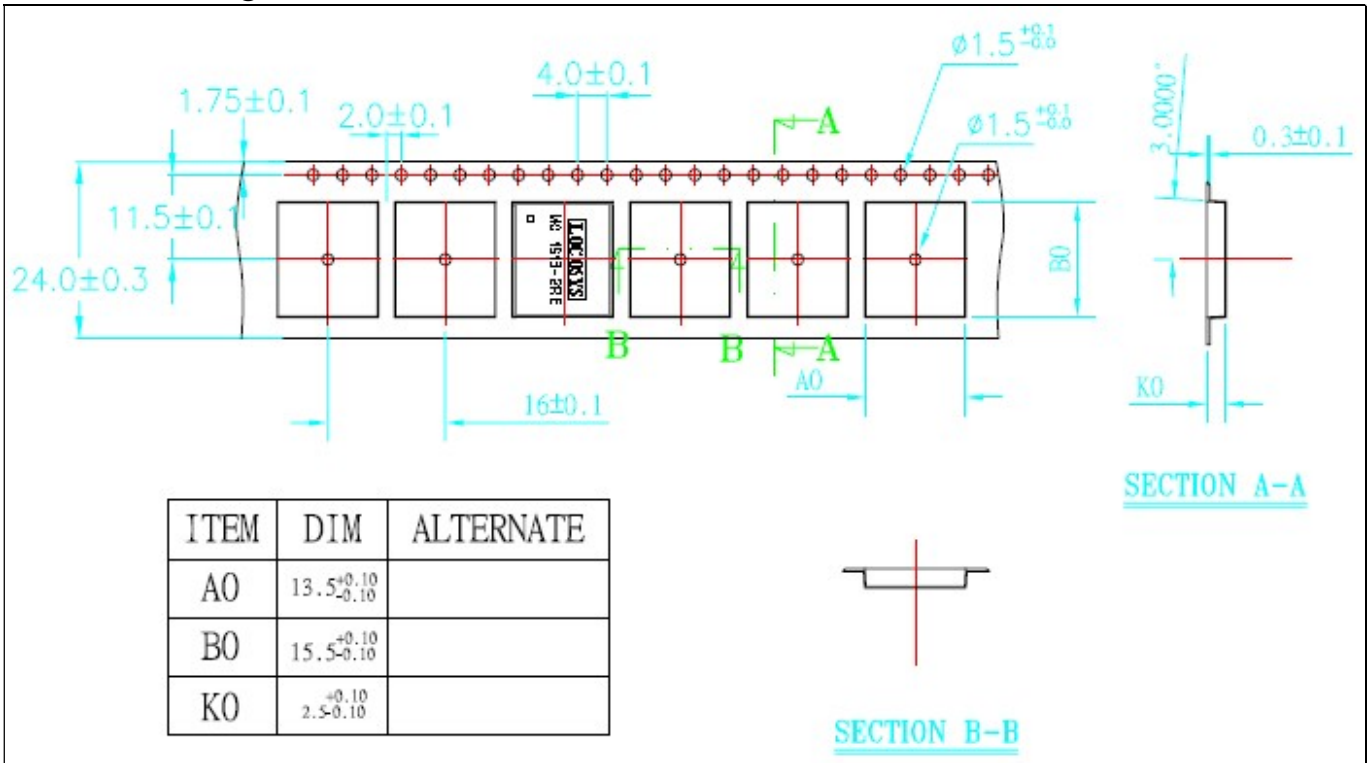
9 Reel Packing information



ITEM	DIM	ALTERNATE
A0	$13.5^{+0.10}_{-0.10}$	
B0	$15.5^{+0.10}_{-0.10}$	
K0	$2.5^{+0.10}_{-0.10}$	

1. 10 sprocket hole pitch cumulative tolerance ±0.20mm.
2. Carrier camber not to exceed 1mm in 100mm.
3. A0 and B0 measured on a plane 0.3mm above the bottom of the pocket.
4. K0 measured from a plane on the inside bottom of the pocket to the top surface of the carrier.
5. All dimensions meet EIA-481-2 requirements.
6. Material: Black Anti-Static Polystyrene.
7. Component load per 13" reel :1000 pcs.

LOCOSYS

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Document change list

Revision 1.0

- First release on November 23, 2012

Revision 1.0 to revision 1.1 (Jun 30, 2015)

- Revised product name from MC-1513-2R to MC-1513-2RE
- Revised chip from MT3337 to MT3337E
- Added support 1PPS synchronize with NMEA output feature
- Added support self-generate orbit prediction to achieve faster cold star feature
- Remove Capable of SBAS (WAAS, EGNOS, MSAS, GAGAN) feature
- Remove Section 5.3.3 AlwaysLocate™ mode feature

Revision 1.1 to revision 1.2 (Jul 15, 2015)

- Remove Section 5.3.2 Periodic mode feature because MT3337E does not support it.

Revision 1.2 to revision 1.3 (Nov 18, 2021)

- Revised autonomous position accuracy in section 4.