



# Commands List

---

**Suitable for the following GNSS Series Product**

Product Type	Model Name
GNSS Module	MG-1010-52Q、MG-1612-52Q
GNSS Smart Antenna	LC20030-52Q、LC20031-52Q、LC20032-52Q
GNSS Mouse	LU23030-52Q、LU23032-52Q、LU23036-52Q

Version: V1.1 (Firmware SDK version 3.2.1)

2024/10/18

LOCOSYS Technology Inc.

20F.-13, No.79, Sec. 1, Xintai 5th Rd.,

Xizhi District, New Taipei City 221, Taiwan

☎ 886-2-8698-3698

☎ 886-2-8698-3699

🌐 [www.locosystech.com](http://www.locosystech.com)

## PAIR Commands

PAIR command is an AIROHA proprietary GNSS data transfer protocol. This protocol is used to configure the GNSS module's parameters, aiding information and to receive notifications from the GNSS module.

The PAIR aligns with the NMEA sentence format to process data more conveniently.

## Command Format

The PAIR packet format with number of bytes allocated for each field is show in the table.

1	4	3	variable	1	1	1	1	1
Preamble	Tracker ID	PktType	DataField	*	CHK1	CHK2	CR	LF

The details of each field in the packet are provided in the table.

Parameter	Description
Preamble	One-byte character. - Default: '\$'
TalkerID	Four-byte character string. - Default: PAIR. Customer can change this string for customization commands.
PktType	Three-byte character string. - From 000 to 999. An identifier used to tell the decoder how to decode the packet.
DataField	Has a variable length depending on the packet type. - A comma symbol ',' must be inserted before each data field to help the decoder process the DataField.
*	One-byte character. - The asterisk symbol is used to mark the end of the DataField.
CHK1, CHK2	One-byte character for each. - CHK1 and CHK2 are the checksum of the data between Preamble and '*'. Please use <code>gnss_app_get_command_checksum</code> or reference <a href="#">Appendix - How to get checksum</a> .
CR, LF	One byte ASCII data for each. - The two bytes are used to identify the end of a packet.

## Command List

The PAIR command list for each packet type is given in the table.

Note:

All Commands will respond with PAIR001 (**PAIR\_ACK**) as the default result. You can check the command result from PAIR001 (**PAIR\_ACK**) parameter.

All command strings shown do not include spaces.

Packet Type	Command	Description
001	<b>PAIR_ACK</b>	Acknowledge of PAIR command.
002	<b>PAIR_GNSS_SUBSYS_POWER_ON</b>	Power on the GNSS system. Include DSP/RF/Clock and other GNSS modules.
003	<b>PAIR_GNSS_SUBSYS_POWER_OFF</b>	Power off GNSS system. Include DSP/RF/Clock and other GNSS modules.
004	<b>PAIR_GNSS_SUBSYS_HOT_START</b>	Hot Start. Use the available data in the NVRAM.
005	<b>PAIR_GNSS_SUBSYS_WARM_START</b>	Warm Start. Not using Ephemeris data at the start.
006	<b>PAIR_GNSS_SUBSYS_COLD_START</b>	Cold Start. Not using the Position, Almanac or Ephemeris data at the start.
008	<b>PAIR_GNSS_SUBSYS_GET_STATUS</b>	Get GNSS subsys status.
010	<b>PAIR_REQUEST_AIDING</b>	Request GNSS system reference data.
011	<b>PAIR_INDICATION_SYSTEM_MESSAGE</b>	GNSS System message indication.
020	<b>PAIR_GET_VERSION</b>	Query the firmware release information.
021	<b>PAIR_GET_SETTING_INFO</b>	Query the customer related setting, such as the firmware release information, DCB values, HW interface, ULP enable and NVRAM auto saving.
023	<b>PAIR_SYSTEM_REBOOT</b>	Reboot GNSS whole chip, including the GNSS submodule and other all CM4 modules.
030	<b>PAIR_COMMON_GET_POS_XYZ</b>	The WGS84 ECEF XYZ Cartesian Position vector (in meters) with an estimated 1-sigma accuracy.
031	<b>PAIR_COMMON_GET_VEL_XYZ</b>	The WGS84 ECEF XYZ Cartesian velocity vector (m/s) with an estimated 1-sigma accuracy.
043	<b>PAIR_COMMON_GET_TOW_WN</b>	Get TOW (Time of week) and WN (Week number)

		information.
050	<b>PAIR_COMMON_SET_FIX_RATE</b>	Set Position Fix Interval.
051	<b>PAIR_COMMON_GET_FIX_RATE</b>	Get Position Fix Interval.
058	<b>PAIR_COMMON_SET_MIN_SNR</b>	Set the minimum SNR of used satellites.
059	<b>PAIR_COMMON_GET_MIN_SNR</b>	Query the minimum SNR of used satellites.
060	<b>PAIR_COMMON_SET_ESTIMATED_NUM</b>	Set the number of estimated fixes when entering the tunnel.
061	<b>PAIR_COMMON_GET_ESTIMATED_NUM</b>	Query the number of estimated fixes when entering the tunnel.
062	<b>PAIR_COMMON_SET_NMEA_OUTPUT_RATE</b>	Set the NMEA sentence output interval of corresponding NMEA type.
063	<b>PAIR_COMMON_GET_NMEA_OUTPUT_RATE</b>	Get the NMEA sentence output interval of corresponding NMEA type.
064	<b>PAIR_COMMON_SET_HACC_LIMIT</b>	Set horizontal accuracy mask. Range from 30m to 200m or 0. GPS only gets the fix when hacc value < mask.
065	<b>PAIR_COMMON_GET_HACC_LIMIT</b>	Query horizontal accuracy mask.
066	<b>PAIR_COMMON_SET_GNSS_SEARCH_MODE</b>	Configure the receiver to start searching for satellites. The setting is available when the NVRAM data is valid.
067	<b>PAIR_COMMON_GET_GNSS_SEARCH_MODE</b>	This command is to get GPS, GLONASS, Galileo, BeiDou, QZSS and NavIC search settings.
068	<b>PAIR_COMMON_SET_HDOP_THRESHOLD</b>	This command is for setting the HDOP threshold.
069	<b>PAIR_COMMON_GET_HDOP_THRESHOLD</b>	This command is to get the HDOP threshold.
070	<b>PAIR_COMMON_SET_STATIC_THRESHOLD</b>	Set the speed threshold for static navigation.
071	<b>PAIR_COMMON_GET_STATIC_THRESHOLD</b>	Query the static navigation speed threshold.
072	<b>PAIR_COMMON_SET_ELEV_MASK</b>	Set satellite elevation mask.
073	<b>PAIR_COMMON_GET_ELEV_MASK</b>	Get satellite elevation mask.
074	<b>PAIR_COMMON_SET_AIC_ENABLE</b>	Enable or disable active interference cancellation function.
075	<b>PAIR_COMMON_GET_AIC_STATUS</b>	Get the status of active interference cancellation function.
076	<b>PAIR_COMMON_SET_DATUM</b>	Set default datum.
077	<b>PAIR_COMMON_GET_DATUM</b>	Get default datum.

080	<b>PAIR_COMMON_SET_NAVIGATION_MODE</b>	Set navigation mode.
081	<b>PAIR_COMMON_GET_NAVIGATION_MODE</b>	Get navigation mode.
086	<b>PAIR_COMMON_SET_DEBUGLOG_OUTPUT</b>	This command is to set enable/disable debug log output in binary format
087	<b>PAIR_COMMON_GET_DEBUGLOG_OUTPUT</b>	Query setting of debug log output.
092	<b>PAIR_COMMON_SET_STATIC_MODE</b>	Enable static mode
093	<b>PAIR_COMMON_GET_STATIC_MODE</b>	Query if current mode is static mode
098	<b>PAIR_COMMON_SET_NMEA_POS_DECIMAL_PRECISION</b>	This command is for setting the digits shown in the NMEA position.
099	<b>PAIR_COMMON_GET_NMEA_POS_DECIMAL_PRECISION</b>	This command is to get NMEA position shown digit mode
100	<b>PAIR_COMMON_SET_NMEA_OUTPUT_MODE</b>	This command is to set NMEA output mode
101	<b>PAIR_COMMON_GET_NMEA_OUTPUT_MODE</b>	This command is to get NMEA output mode
130	<b>PAIR_COMMON_SET_SV_BLACKLIST</b>	Set sv blacklist for selected constellation, which excludes specific PRNs and does not search for them.
131	<b>PAIR_COMMON_GET_SV_BLACKLIST</b>	Get sv blacklist for selected constellation, which excludes specific PRNs and does not search for them.
144	<b>PAIR_COMMON_SET_STATIC_THRESHOLD_ADVANCE</b>	Set the position difference threshold for static navigation.
145	<b>PAIR_COMMON_GET_STATIC_THRESHOLD_ADVANCE</b>	Query the static navigation position difference threshold.
154	<b>PAIR_COMMON_SET_RLM_OUTPUT_ENABLE</b>	Enable to output Return Link Message from navigation data.
155	<b>PAIR_COMMON_GET_RLM_OUTPUT_STATUS</b>	Query output Return Link Message status.
158	<b>PAIR_COMMON_SET_B1c_ENABLE</b>	Enable B1c.
159	<b>PAIR_COMMON_GET_B1c_STATUS</b>	Query output B1c enable status.
160	<b>PAIR_COMMON_SET_IMMEDIATE_SPEED_MODE</b>	Enable immediate speed mode.

161	<b>PAIR_COMMON_GET_IMMEDIATE_SPEED_MODE</b>	Query if immediate speed mode is enabled.
162	<b>PAIR_COMMON_SET_2D_FIX_ENABLE</b>	Enable 2D fix mode.
163	<b>PAIR_COMMON_GET_2D_FIX_ENABLE</b>	Query if 2D fix mode is enabled
164	<b>PAIR_COMMON_SET_ODOMETER_ENABLE</b>	Enable the odometer function.
165	<b>PAIR_COMMON_GET_ODOMETER_STATUS</b>	Query the status of the odometer function and the traveling distance value if the function is enabled.
400	<b>PAIR_DGPS_SET_MODE</b>	DGPS correction data source mode.
401	<b>PAIR_DGPS_GET_MODE</b>	Query the DGPS data source mode.
410	<b>PAIR_SBAS_ENABLE</b>	Enable searching a SBAS satellite or not.
411	<b>PAIR_SBAS_GET_STATUS</b>	Query the status of SBAS to whether it is enabled.
412	<b>PAIR_SBAS_GET_SAT_INFO</b>	Get information about the SBAS satellites, such as SVid, SNR, azimuth, and elevation.
420	<b>PAIR_SLAS_ENABLE</b>	Enable the QZSS SLAS (Sub-meter Level Augmentation Service) operation.
421	<b>PAIR_SLAS_GET_STATUS</b>	Query the status of SLAS to check whether it is enabled.
430	<b>PAIR_RTCM_SET_INPUT_VERSION</b>	Set RTCM input version.
431	<b>PAIR_RTCM_GET_INPUT_VERSION</b>	Get RTCM input version.
432	<b>PAIR_RTCM_SET_OUTPUT_MODE</b>	Set RTCM output mode.
433	<b>PAIR_RTCM_GET_OUTPUT_MODE</b>	Get RTCM output mode.
434	<b>PAIR_RTCM_SET_OUTPUT_ANT_PNT</b>	This command is to set enable/disable stationary antenna reference point for RTCM output.
435	<b>PAIR_RTCM_GET_OUTPUT_ANT_PNT</b>	Query setting of stationary antenna reference point for RTCM output.
436	<b>PAIR_RTCM_SET_OUTPUT_EPHEMERIS</b>	This command is to set enable/disable RTCM output with satellite ephemeris.
437	<b>PAIR_RTCM_GET_OUTPUT_EPHEMERIS</b>	Query setting of RTCM satellite ephemeris output.
442	<b>PAIR_RTCM_SET_STATION_ID</b>	This command is to set RTCM output station id
443	<b>PAIR_RTCM_GET_STATION_ID</b>	Query setting of RTCM station id
496	<b>PAIR_EPOC_ENABLE</b>	Enable or Disable EPOC
498	<b>PAIR_EPOC_SET_CONFIG</b>	Set EPOC Configuration
507	<b>PAIR_EPOC_CLEAR_DATA</b>	Clear All EPOC data in NVRAM

508	<b>PAIR_EPOC_GET_STATUS</b>	Get EPOC status
509	<b>PAIR_EPOC_GET_PREDICTION_STATUS</b>	Get EPOC prediction status
510	<b>PAIR_NVRAM_AUTO_SAVING_ENABLE</b>	Enable/Disable navigation data auto saving from RTC RAM to flash.
511	<b>PAIR_NVRAM_SAVE_NAVIGATION_DATA</b>	Save current navigation data from RTC RAM to flash.
512	<b>PAIR_NVRAM_CLEAR_NAVIGATION_DATA</b>	Clear navigation data in both RTC RAM and flash.
513	<b>PAIR_NVRAM_SAVE_SETTING</b>	Save the current configuration from RTC RAM to flash.
514	<b>PAIR_NVRAM_RESTORE_DEFAULT_SETTING</b>	Clear the current configuration and restore the default settings.
596	<b>PAIR_TIME_GET_CURRENT_TOW</b>	Get current time of week in milliseconds.
597	<b>PAIR_TIME_GET_GNSS_TOW</b>	Get the last GNSS epoch's time of week in milliseconds.
650	<b>PAIR_LOW_POWER_ENTRY_RTC_MODE</b>	Shutdown all systems, including GNSS and other CM4 modules.
680	<b>PAIR_GLP_ENABLE</b>	This command is to activate low-power GLP mode.
681	<b>PAIR_GLP_GET_STATUS</b>	This command is to get low-power GLP mode setting
690	<b>PAIR_PERIODIC_SET_MODE</b>	This command is used to set Periodic Power Saving Mode Settings.
691	<b>PAIR_PERIODIC_GET_MODE</b>	This command is used to get Periodic Power Saving Mode Settings.
720	<b>PAIR_DTM_ENABLE</b>	The GNSS Duty tracking mode is a duty cycle concept to ensure good performance
721	<b>PAIR_DTM_GET_STATUS</b>	This command is to get Duty tracking mode configuration setting.
730	<b>PAIR_FLP_ENABLE</b>	The fitness low power mode is a concept to ensure good performance
731	<b>PAIR_FLP_GET_STATUS</b>	This command is to get fitness low-power mode configuration setting.
732	<b>PAIR_ALP_ENABLE</b>	The adaptive low power mode is a concept to ensure good performance
733	<b>PAIR_ALP_GET_STATUS</b>	This command is to get adaptive low-power mode



		configuration setting.
752	<b>PAIR_PPS_SET_CONFIG_CMD</b>	Configure the PPS settings.
753	<b>PAIR_PPS_SET_TIMING_PRODUCT</b>	The timing product mode will enhance the PPS output timing accuracy.
755	<b>PAIR_PPS_SET_TIMETAG</b>	Set enable/disable output time tag and time base.
756	<b>PAIR_PPS_GET_TIMETAG_CONFIG</b>	Get time tag configuration including output status and time base.
757	<b>PAIR_PPS_SET_FALLING_EDGE_TRIGGER</b>	Set PPS trigger from rising edge to falling edge
758	<b>PAIR_PPS_GET_FALLING_EDGE_TRIGGER</b>	Get PPS trigger mode
763	<b>PAIR_PPS_GET_CONFIG</b>	Get PPS config from PAIR750 / PAIR752.
830	<b>PAIR_RAW_ENABLE</b>	Set enable/disable output binary raw measurement
831	<b>PAIR_RAW_GET_STATUS</b>	Get enable/disable output binary raw measurement
864	<b>PAIR_IO_SET_BAUDRATE</b>	Set port baud rate configuration.
865	<b>PAIR_IO_GET_BAUDRATE</b>	Get port baud rate configuration.
866	<b>PAIR_IO_SET_FLOW_CONTROL</b>	Set port flow control configuration.
867	<b>PAIR_IO_GET_FLOW_CONTROL</b>	Get port SW flow control configuration.
890	<b>PAIR_GEOFENCE_SET_CONFIG</b>	This command is used to set Geofencing configuration.
891	<b>PAIR_GEOFENCE_GET_CONFIG</b>	This command is used to get Geofencing configuration.
892	<b>PAIR_GEOFENCE_SET_GPIO_POLARITY</b>	This command is used to set GPIO polarity for geofencing combined state.
900	<b>PAIR_LOCUS_ENABLE</b>	Enable or disable LOCUS save data.
901	<b>PAIR_LOCUS_GET_STATUS</b>	Get LOCUS status.
902	<b>PAIR_LOCUS_SET_MODE</b>	Set LOCUS saving mode.
903	<b>PAIR_LOCUS_GET_MODE</b>	Get LOCUS saving mode.
904	<b>PAIR_LOCUS_SET_THRESHOLD</b>	Set LOCUS mode threshold.
905	<b>PAIR_LOCUS_GET_THRESHOLD</b>	Get LOCUS mode threshold.
906	<b>PAIR_LOCUS_CLEAR</b>	Clear LOCUS Data.
907	<b>PAIR_LOCUS_LOG_NOW</b>	Save current location data.
908	<b>PAIR_LOCUS_GET_DATA</b>	Get all record data.
909	<b>PAIR_LOCUS_GET_RECORD_NUM</b>	Get total record number.



<p>PAIR_ACK</p>	<p><b>[Packet Type]</b> 001</p> <p><b>[Command]</b> PAIR_ACK</p> <p><b>[Description]</b> Acknowledge of PAIR command.</p> <p><b>[Return]</b> \$PAIR001,Command_ID,Result*CS&lt;CR&gt;&lt;LF&gt; Command_ID: The command / packet type the acknowledge responds. Result: The result of the command. 0: The command was successfully sent. 1: The command is processing. You must wait for the result. 2: Sending the command failed. 3: This command ID is not supported. 4: Command parameter error. Out of range / some parameters were lost / checksum error. 5: MNL service is busy. You can try again soon.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR666*3C\r\n</p> <p>Response: \$PAIR001,666,0*3D\r\n ==&gt; Success</p> </div> <p><b>[Note]</b> This item is the response of commands. The GNSS system automatically sends this command. Do not directly send it to the GNSS system.</p>
<p>PAIR_GNSS_SUBSYS_POWER_ON</p>	<p><b>[Packet Type]</b> 002</p> <p><b>[Command]</b> PAIR_GNSS_SUBSYS_POWER_ON</p> <p><b>[Description]</b> Power on the GNSS system. Include DSP/RF/Clock and other GNSS modules.</p> <p><b>[Data Field]</b> \$PAIR002*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR002*38\r\n</p> </div>

	<p>Response:</p> <p>\$PAIR001,002,1*38\r\n ==&gt; The power on process is running. Please wait a moment.</p> <p>\$PAIR001,002,0*39\r\n ==&gt; Power on was successful.</p> <p><b>[Note]</b></p> <p>Please send this command before using any location service.</p>
PAIR_GNSS_SUBSYS_POWER_OFF	<p><b>[Packet Type]</b></p> <p>003</p> <p><b>[Command]</b></p> <p>PAIR_GNSS_SUBSYS_POWER_OFF</p> <p><b>[Description]</b></p> <p>Power off GNSS system. Include DSP/RF/Clock and other GNSS modules.</p> <p>CM4 also can receive commands (Include the AT command / the race Command / the part of PAIR command which is not dependent on DSP.) after sending this command.</p> <p><b>[Data Field]</b></p> <p>\$PAIR003*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <p>\$PAIR003*39\r\n</p> <p>Response:</p> <p>\$PAIR001,003,1*39\r\n ==&gt; The power off process is running. Please wait a moment.</p> <p>\$PAIR001,003,0*38\r\n ==&gt; Power off was successful.</p> <p><b>[Note]</b></p> <p>The location service is not available after this command is executed.</p> <p>The system can still receive configuration PAIR commands. The application is running if necessary.</p> <p>CM4 will go to sleep if the application is not working at this time. The system can be awoken by the GNSS_DATA_IN_EINT pin after going to sleep.</p>
PAIR_GNSS_SUBSYS_HOT_START	<p><b>[Packet Type]</b></p> <p>004</p> <p><b>[Command]</b></p> <p>PAIR_GNSS_SUBSYS_HOT_START</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b></p> <p>Hot Start. Use the available data in the NVRAM.</p>

	<p><b>[Data Field]</b></p> <p><b>\$PAIR004*CS&lt;CR&gt;&lt;LF&gt;[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <hr/> <p>Send:</p> <p>\$PAIR004*3E\r\n</p> <p>Response:</p> <p>\$PAIR001,004,0*3F\r\n ==&gt; Success</p>
PAIR_GNSS_SUBSYS_WARM_START	<p><b>[Packet Type]</b></p> <p>005</p> <p><b>[Command]</b></p> <p>PAIR_GNSS_SUBSYS_WARM_START</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b></p> <p>Warm Start. Not using Ephemeris data at the start.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR005*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <hr/> <p>Send:</p> <p>\$PAIR005*3F\r\n</p> <p>Response:</p> <p>\$PAIR001,005,0*3E\r\n ==&gt; Success</p>
PAIR_GNSS_SUBSYS_COLD_START	<p><b>[Packet Type]</b></p> <p>006</p> <p><b>[Command]</b></p> <p>PAIR_GNSS_SUBSYS_COLD_START</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b></p> <p>Cold Start. Not using the Position, Almanac or Ephemeris data at the start.</p> <p><b>[Data Field]</b></p>

	<p><b>\$PAIR006*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR006*3C\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,006,0*3D\r\n ==&gt; Success</p>
PAIR_GNSS_SUBSYS_GET_STATUS	<p><b>[Packet Type]</b></p> <p>008</p> <p><b>[Command]</b></p> <p>PAIR_GNSS_SUBSYS_GET_STATUS</p> <p><b>[Description]</b></p> <p>Get GNSS subsys status.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR008*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR008,&lt;status&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p style="padding-left: 20px;">status: the status of GNSS subsys.</p> <p style="padding-left: 40px;">0: The GNSS subsys has powered on.</p> <p style="padding-left: 40px;">1: The GNSS subsys is powered off.</p> <p><b>[Example]</b></p> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR008*32\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,008,0*33\r\n ==&gt; Success</p> <p style="padding-left: 20px;">\$PAIR008,1,0*33\r\n ==&gt; GNSS subsys has powered on.</p>
PAIR_REQUEST_AIDING	<p><b>[Packet Type]</b></p> <p>010</p> <p><b>[Command]</b></p> <p>PAIR_REQUEST_AIDING</p> <p><b>[Description]</b></p> <p>Request GNSS system reference data.</p> <p><b>[Return]</b></p> <p><b>\$PAIR010,&lt;Type&gt;,&lt;GNSS_System&gt;,&lt;Week_Number&gt;,&lt;Time_of_Week&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p>

	<p>Type: The data type.</p> <ul style="list-style-type: none"> <li>0: Need to update EPO data.</li> <li>1: Need to update the time.</li> <li>2: Need to update the location.</li> </ul> <p>GNSS_System: The GNSS system type is needed.</p> <ul style="list-style-type: none"> <li>0: Need GPS data.</li> <li>1: Need GLONASS data.</li> <li>2: Need GALILEO data.</li> <li>3: Need BEIDOU data.</li> <li>4: Need QZSS data.</li> </ul> <p>Week_Number: The current GNSS week number.</p> <p>Time_of_Week: The current GNSS time of week.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Response:</p> <p>\$PAIR010,0,0,2044,369413*33\r\n ==&gt; Please send GPS EPO data when this command is received.</p> <p>\$PAIR010,1,-1*16\r\n ==&gt; Please send reference time when this command is received.</p> <p>\$PAIR010,2,-1*15\r\n ==&gt; Please send reference location when this command is received.</p> </div> <p><b>[Note]</b></p> <p>The GNSS system automatically sends this command. Please do not actively send it to the GNSS system.</p>
<p>PAIR_INDICATION_SYSTEM_MESSAGE</p>	<p><b>[Packet Type]</b></p> <p>011</p> <p><b>[Command]</b></p> <p>PAIR_INDICATION_SYSTEM_MESSAGE</p> <p><b>[Description]</b></p> <p>GNSS System message indication.</p> <p><b>[Data Field]</b></p> <p>\$PAIR011,&lt;Type&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Type:</p> <p>"1", Notification for GNSS system startup</p> <p><b>[Return]</b></p> <p>NONE</p> <p><b>[Example]</b></p> <p>\$PAIR011,001*27</p> <p><b>[Note]</b></p> <p>The GNSS system automatically sends this command. Please do not actively send it to the GNSS system.</p>

PAIR_GET_VERSION	<p><b>[Packet Type]</b> 020</p> <p><b>[Command]</b> PAIR_GET_VERSION</p> <p><b>[Description]</b> Query the firmware release information.</p> <p><b>[Data Field]</b> \$PAIR020*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. \$PAIR020,&lt;Project Version&gt;,&lt;Frequency&gt;,&lt;SW package&gt;,&lt;Service version&gt;,&lt;Service build time&gt;,&lt;DSP L1 rom version&gt;,&lt;DSP L1 ram version&gt;,&lt;DSP L5 rom version&gt;,&lt;DSP L5 ram version&gt;,&lt;Kernel version&gt;,&lt;Kernel build time&gt;,&lt;KF version&gt;,&lt;KF build time&gt;,&lt;RTK version&gt;,&lt;RTK build time&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>Project Version:          &lt;Project_board&gt;_&lt;SDK version&gt;_&lt;SDK Build time&gt;          &lt;Project_board&gt; AG3352Q / AG3352B          &lt;SDK version&gt; VX.Y.Z - X:Major Y:Minor Z. Bug fix          &lt;SDK build time&gt; YYYYMMDD          Note: Max length of this field is 100 Bytes          Ex:          AG3352B_V2.0.0_20220318</p> <p>Frequency:          S: single          D: dual</p> <p>SW package:          N: normal          W: raw          R: RTK          I: NavIC</p> <p>Service version:          mnl_service version in 7 characters          Ex:          xxxxxxx</p> <p>Service build time:          mnl_service library build time          Ex:          yyMMDDhhmm</p> <p>DSP L1 rom version:</p>
------------------	---

Null before first power on

Ex:

xx

DSP L1 ram version:

Null before first power on

Ex:

xxx

DSP L5 rom version:

Null for L1 only project

Null before first power on

Ex:

xx

DSP L5 ram version:

Null for L1 only project

Null before first power on

Ex:

xxx

Kernel version:

mnl\_kernel version in 7 characters

Ex:

xxxxxxx

Kernel build time:

mnl\_kernel library build time

Ex:

yyMMDDhhmm

KF version:

mnl\_kf version in 7 characters

Ex:

xxxxxxx

KF build time:

mnl\_kf library build time

Ex:

yyMMDDhhmm

RTK version:

RTK version in 7 characters

anything other than the RTK project

Ex:

xxxxxxx

RTK build time:



	<p>RTK library build time Null for not RTK project Ex: yyMMDDhhmm</p> <p><b>[Example]</b></p> <p>Send: \$PAIR020*38\r\n</p> <p>Response: \$PAIR001,020,0*39\r\n ==&gt; Success \$PAIR020,AG3352B_V2.0.0_YYYYMMDD,S,N,xxxxxxx,yyMMDDhhmm,xx,xxx,xx,xxx,xx xxxxx,yyMMDDhhmm,xxxxxxx,yyMMDDhhmm,*,*56\r\n</p>
<p>PAIR_GET_SETTING _INFO</p>	<p><b>[Packet Type]</b> 021</p> <p><b>[Command]</b> PAIR_GET_SETTING_INFO</p> <p><b>[Description]</b> Query the customer related setting, such as the firmware release information, DCB values, HW interface, ULP enable and NVRAM auto saving.</p> <p><b>[Data Field]</b> \$PAIR021*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. \$PAIR021,&lt;Project Version&gt;,&lt;Frequency&gt;,&lt;SW package&gt;,&lt;Service version&gt;,&lt;Service build time&gt;,&lt;DSP L1 rom version&gt;,&lt;DSP L1 ram version&gt;,&lt;DSP L5 rom version&gt;,&lt;DSP L5 ram version&gt;,&lt;Kernel version&gt;,&lt;Kernel build time&gt;,&lt;KF version&gt;,&lt;KF build time&gt;,&lt;RTK version&gt;,&lt;RTK build time&gt;,&lt;GPS DCB&gt;,&lt;GAL DCB&gt;,&lt;BDS DCB&gt;,&lt;QZS DCB&gt;,&lt;TCXO Freq Error&gt;,&lt;Gain&gt;,&lt;SWPRT Info&gt;,&lt;ULP enable&gt;,&lt;NVRAM Auto Saving&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>Refer to PAIR020 (Project Version,Frequency,....,RTK build time)</p> <p>GPS DCB : The Differential Code Biases value for GPS.</p> <p>GAL DCB : The Differential Code Biases value for GAL.</p> <p>BDS DCB : The Differential Code Biases value for BDS.</p> <p>QZS DCB : The Differential Code Biases value for QZS.</p> <p>TCXO Frequency error :</p> <ul style="list-style-type: none"> <li>'0' 0.5ppm</li> <li>'1' 1.0ppm</li> <li>'2' 1.5ppm</li> <li>'3' 2.0ppm</li> </ul>

	<p>Gain : '0' High gain           '1' Low gain</p> <p>SWPRT Check :</p> <p>    ##: No Check     #P: Pass     #F: Fail</p> <p>ULP enable :</p> <p>    '0' disable     '1' enable</p> <p>NVRAM Auto Saving :</p> <p>    '0' Disable     '1' Enable</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:     \$PAIR021*39\r\n</p> <p>Response:     \$PAIR001,021,0*38\r\n     \$PAIR021,AG3352B_V2.0.0_YYYYMMDD,S,N,xxxxxxx,yyMMDDhhmm,xx,xxx,xx,xxx,xx     xxxxx,yyMMDDhhmm,xxxxxxx,yyMMDDhhmm,-15.48,-15.48,-14.02,-15.48,0,1,##,0,0*59\r\n</p> </div>
<p>PAIR_SYSTEM_REB OOT</p>	<p><b>[Packet Type]</b></p> <p>023</p> <p><b>[Command]</b></p> <p>PAIR_SYSTEM_REBOOT</p> <p><b>[Description]</b></p> <p>Reboot GNSS whole chip, including the GNSS submodule and other all CM4 modules.</p> <p><b>[Data Field]</b></p> <p>\$PAIR023*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:     \$PAIR023*3B\r\n</p> <p>Response:     Reboot directly. Without Response.</p> </div>
<p>PAIR_COMMON_GE T_POS_XYZ</p>	<p><b>[Packet Type]</b></p> <p>030</p>

	<p><b>[Command]</b> PAIR_COMMON_GET_POS_XYZ</p> <p><b>[Note]</b> This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b> The WGS84 ECEF XYZ Cartesian Position vector (in meters) with an estimated 1-sigma accuracy.</p> <p><b>[Data Field]</b> \$PAIR030*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <a href="#">PAIR_ACK</a> for send result. 2. \$PAIR030,&lt;X&gt;,&lt;Y&gt;,&lt;Z&gt;,&lt;Acc&gt;*CS&lt;CR&gt;&lt;LF&gt; X: WGS84 ECEF X Cartesian position (in meters). Y: WGS84 ECEF Y Cartesian position (in meters). Z: WGS84 ECEF Z Cartesian position (in meters). Acc: 3-dimensional position space 1-sigma accuracy estimate (in meters).</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR030*39\r\n</p> <p>Response: \$PAIR001,030,0*38\r\n ==&gt; Success \$PAIR030,-2984524.0,4966958.3,2656485.3,3.0*14\r\n ==&gt; The WGS84 ECEF XYZ Cartesian Position.</p> </div>
<p>PAIR_COMMON_GET_VEL_XYZ</p>	<p><b>[Packet Type]</b> 031</p> <p><b>[Command]</b> PAIR_COMMON_GET_VEL_XYZ</p> <p><b>[Note]</b> This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b> The WGS84 ECEF XYZ Cartesian velocity vector (m/s) with an estimated 1-sigma accuracy.</p> <p><b>[Data Field]</b> \$PAIR031*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <a href="#">PAIR_ACK</a> for send result.</p>

	<p>2. \$PAIR031,&lt;VX&gt;,&lt;VY&gt;,&lt;VZ&gt;,&lt;Acc&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>VX: WGS84 ECEF X Cartesian velocity vector (m/s).                  VY: WGS84 ECEF Y Cartesian velocity vector (m/s).                  VZ: WGS84 ECEF Z Cartesian velocity vector (m/s).                  Acc: 3-dimensional speed 1-sigma accuracy (m/s).</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR031*38\r\n</p> <p>Response:                      \$PAIR001,031,0*39\r\n ==&gt; Success                      \$PAIR031,0.19,-0.07,-0.11,0.49*3A\r\n ==&gt; The WGS84 ECEF XYZ Cartesian Velocity.</p> </div>
PAIR_COMMON_GET_TOW_WN	<p><b>[Packet Type]</b> 043</p> <p><b>[Command]</b> PAIR_COMMON_GET_TOW_WN</p> <p><b>[Description]</b> Get TOW (Time of week) and WN (Week number) information.</p> <p><b>[Data Field]</b> \$PAIR043*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. \$PAIR043,&lt;TOW&gt;,&lt;WN&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>TOW: GNSS Time of week                  WN: GNSS Week number</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR043*3D\r\n</p> <p>Response:                      \$PAIR001,043,0*3C\r\n                      \$PAIR043,2065,394925.000*22\r\n</p> </div>
PAIR_COMMON_SET_FIX_RATE	<p><b>[Packet Type]</b> 050</p> <p><b>[Command]</b> PAIR_COMMON_SET_FIX_RATE</p> <p><b>[Description]</b> Set Position Fix Interval.</p>

	<p>If set less than 1000 ms, ASCII NMEA will automatically increase the update interval in order to decrease IO throughput.</p> <p>It will return false if the operating voltage setting is not correct.                  (Any fix interval change between 1Hz &lt;-&gt; multihz causes GNSS to power on/off)</p> <p><b>[Data Field]</b>  <b>\$PAIR050,&lt;Fix_Interval&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Fix_Interval: Position fix interval in milliseconds (ms). [Range: 100 ~ 1000]</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR050,1000*12\r\n</p> <p>Response:                      \$PAIR001,050,0*3E\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GET_FIX_RATE	<p><b>[Packet Type]</b>                  051</p> <p><b>[Command]</b>                  PAIR_COMMON_GET_FIX_RATE</p> <p><b>[Description]</b>                  Get Position Fix Interval.</p> <p><b>[Data Field]</b>  <b>\$PAIR051*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR050,&lt;Fix_Interval&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></li> </ol> <p>Fix_Interval: Position fix interval in milliseconds (ms). [Range: 100 ~ 1000]</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR051*3E\r\n</p> <p>Response:                      \$PAIR001,051,0*3F\r\n ==&gt; Success                      \$PAIR051,1000*13\r\n</p> </div>
PAIR_COMMON_SET_MIN_SNR	<p><b>[Packet Type]</b>                  058</p> <p><b>[Command]</b>                  PAIR_COMMON_SET_MIN_SNR</p>

	<p><b>[Description]</b> Set the minimum SNR of used satellites.</p> <p><b>[Data Field]</b> \$PAIR058,&lt;MIN_SNR&gt;*CS&lt;CR&gt;&lt;LF&gt; MIN_SNR: Minimum SNR threshold of used satellites. (Valid range: 9~37, default value: 9)</p> <p><b>[Return]</b> 1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR058,15*1F\r\n ==&gt; Set the minimum SNR threshold to 15, the chip would not use the satellite which SNR is smaller than 15.</p> <p>Response: \$PAIR001,058,0*36\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GET_MIN_SNR	<p><b>[Packet Type]</b> 059</p> <p><b>[Command]</b> PAIR_COMMON_GET_MIN_SNR</p> <p><b>[Description]</b> Query the minimum SNR of used satellites.</p> <p><b>[Data Field]</b> \$PAIR059*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. PAIR_ACK for send result. 2. \$PAIR059,&lt;MIN_SNR&gt;*CS&lt;CR&gt;&lt;LF&gt; MIN_SNR: Minimum SNR threshold of used satellites. (Valid range: 9~37, default value: 9)</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR059*36\r\n</p> <p>Response: \$PAIR001,059,0*37\r\n ==&gt; Success \$PAIR059,15*1E\r\n</p> </div>
PAIR_COMMON_SET_ESTIMATED_NUM	<p><b>[Packet Type]</b> 060</p> <p><b>[Command]</b> PAIR_COMMON_SET_ESTIMATED_NUM</p>

	<p><b>[Description]</b> Set the number of estimated fixes when entering the tunnel.</p> <p><b>[Data Field]</b> \$PAIR060,&lt;NUM_ESTIMATED&gt;*CS&lt;CR&gt;&lt;LF&gt; NUM_ESTIMATED: Number of estimated fixes. (Valid range: 0~500, default value: 0)</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR060,0*20\r\n ==&gt; Disable the estimated fix when entering the tunnel.</p> <p>Response: \$PAIR001,060,0*3D\r\n ==&gt; Success</p> <p>Send: \$PAIR060,3*23\r\n ==&gt; Keep outputting three fixes when entering the tunnel.</p> <p>Response: \$PAIR001,060,0*3D\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GET_ESTIMATED_NUM	<p><b>[Packet Type]</b> 061</p> <p><b>[Command]</b> PAIR_COMMON_GET_ESTIMATED_NUM</p> <p><b>[Description]</b> Query the number of estimated fixes when entering the tunnel.</p> <p><b>[Data Field]</b> \$PAIR061*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result. 2. \$PAIR061,&lt;NUM_ESTIMATED&gt;*CS&lt;CR&gt;&lt;LF&gt; NUM_ESTIMATED: Number of estimated fixes. (Valid range: 0~500, default value: 0)</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR061*3D\r\n</p> <p>Response: \$PAIR001,061,0*3C\r\n ==&gt; Success \$PAIR061,0*21\r\n ==&gt; The user disabled the estimated fix</p> </div>
PAIR_COMMON_SEND_NMEA_OUTPUT_	<p><b>[Packet Type]</b> 062</p>



<p>RATE</p>	<p><b>[Command]</b></p> <p>PAIR_COMMON_SET_NMEA_OUTPUT_RATE</p> <p><b>[Description]</b></p> <p>Set the NMEA sentence output interval of corresponding NMEA type.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR062,&lt;Type&gt;,&lt;Output_Rate&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Type: NMEA Type</p> <p>-1 Reset all sentence to default value.</p> <p>0 NMEA_SEN_GGA, // GGA interval - GPS Fix Data</p> <p>1 NMEA_SEN_GLL, // GLL interval - Geographic Position - Latitude longitude</p> <p>2 NMEA_SEN_GSA, // GSA interval - GNSS DOPS and Active Satellites</p> <p>3 NMEA_SEN_GSV, // GSV interval - GNSS Satellites in View</p> <p>4 NMEA_SEN_RMC, // RMC interval - Recommended Minimum Specific GNSS Sentence</p> <p>5 NMEA_SEN_VTG, // VTG interval - Course Over Ground and Ground Speed</p> <p>6 NMEA_SEN_ZDA, // ZDA interval - Time &amp; Date</p> <p>7 NMEA_SEN_GRS, // GRS interval - GNSS Range Residuals</p> <p>8 NMEA_SEN_GST, // GST Interval - GNSS Pseudorange Error Statistics</p> <p>9 NMEA_SEN_GNS, // GNS Interval - GNSS Fix Data</p> <p>10 NMEA_SEN_DTM, // DTM Interval - Local geodetic datum and datum offsets from a reference datum</p> <p>Output_Rate: Output interval setting (Valid range: 0~20, default value: 1)</p> <p>0 - Disabled or not supported sentence</p> <p>1 - Output once every one position fix</p> <p>2 - Output once every two position fixes</p> <p>3 - Output once every three position fixes</p> <p>4 - Output once every four position fixes</p> <p>5 - Output once every five position fixes</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR062,0,3*3D\r\n</p> <p>Response:</p> <p>\$PAIR001,062,0*3F\r\n ==&gt; Success</p> </div>
<p>PAIR_COMMON_GE T_NMEA_OUTPUT_ RATE</p>	<p><b>[Packet Type]</b></p> <p>063</p> <p><b>[Command]</b></p>

**PAIR\_COMMON\_GET\_NMEA\_OUTPUT\_RATE**

**[Description]**

Get the NMEA sentence output interval of corresponding NMEA type.

**[Data Field]**

**\$PAIR063,<Type>\*CS<CR><LF>**

Type: NMEA Type

-1 return all sentence configuration.

- 0 NMEA\_SEN\_GGA, // GGA interval - GPS Fix Data
- 1 NMEA\_SEN\_GLL, // GLL interval - Geographic Position - Latitude longitude
- 2 NMEA\_SEN\_GSA, // GSA interval - GNSS DOPS and Active Satellites
- 3 NMEA\_SEN\_GSV, // GSV interval - GNSS Satellites in View
- 4 NMEA\_SEN\_RMC, // RMC interval - Recommended Minimum Specific GNSS Sentence
- 5 NMEA\_SEN\_VTG, // VTG interval - Course Over Ground and Ground Speed
- 6 NMEA\_SEN\_ZDA, // ZDA interval - Time & Date
- 7 NMEA\_SEN\_GRS, // GRS interval - GNSS Range Residuals
- 8 NMEA\_SEN\_GST, // GST Interval - GNSS Pseudorange Error Statistics
- 9 NMEA\_SEN\_GNS, // GNS Interval - GNSS Fix Data
- 10 NMEA\_SEN\_DTM, // DTM Interval - Local geodetic datum and datum offsets from a

reference datum

**[Return]**

1. **PAIR\_ACK** for send result.
2. **\$PAIR063,<Type>,<Output\_Rate>\*CS<CR><LF>**

Type: NMEA Type

- 0 NMEA\_SEN\_GGA, // GGA interval - GPS Fix Data
- 1 NMEA\_SEN\_GLL, // GLL interval - Geographic Position - Latitude longitude
- 2 NMEA\_SEN\_GSA, // GSA interval - GNSS DOPS and Active Satellites
- 3 NMEA\_SEN\_GSV, // GSV interval - GNSS Satellites in View
- 4 NMEA\_SEN\_RMC, // RMC interval - Recommended Minimum Specific GNSS Sentence
- 5 NMEA\_SEN\_VTG, // VTG interval - Course Over Ground and Ground Speed
- 6 NMEA\_SEN\_ZDA, // ZDA interval - Time & Date
- 7 NMEA\_SEN\_GRS, // GRS interval - GNSS Range Residuals
- 8 NMEA\_SEN\_GST, // GST Interval - GNSS Pseudorange Error Statistics
- 9 NMEA\_SEN\_GNS, // GNS Interval - GNSS Fix Data
- 10 NMEA\_SEN\_DTM, // DTM Interval - Local geodetic datum and datum offsets from a

reference datum

Output\_Rate: Output interval setting (Valid range: 0~20, default value: 1)

- 0 - Disabled or not supported sentence
- 1 - Output once every one position fix
- 2 - Output once every two position fixes

	<p>3 - Output once every three position fixes                  4 - Output once every four position fixes                  5 - Output once every five position fixes</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR063,0*23\r\n</p> <p>Response:                      \$PAIR001,063,0*3E\r\n ==&gt; Success                      \$PAIR063,0,3*3C\r\n</p> </div>
PAIR_COMMON_SE T_HACC_LIMIT	<p><b>[Packet Type]</b>                  064</p> <p><b>[Command]</b>                  PAIR_COMMON_SET_HACC_LIMIT</p> <p><b>[Description]</b>                  Set horizontal accuracy mask. Range from 30m to 200m or 0. GPS only gets the fix when hacc value &lt; mask.</p> <p><b>[Data Field]</b>                  \$PAIR064,&lt;HaccMask&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>HaccMask:                  30~200: enable hacc mask feature. (Units: meter)                  0 [Default Value]: disable hacc mask feature.</p> <p><b>[Return]</b>                  1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR064,50*11\r\n</p> <p>Response:                      \$PAIR001,064,0*39\r\n ==&gt; Success</p> </div> <p><b>[Note]</b>                  If horizontal accuracy &gt; HaccMask is in use. The GNSS system will not output NMEA sentences.</p>
PAIR_COMMON_GE T_HACC_LIMIT	<p><b>[Packet Type]</b>                  065</p> <p><b>[Command]</b>                  PAIR_COMMON_GET_HACC_LIMIT</p> <p><b>[Description]</b>                  Query horizontal accuracy mask.</p> <p><b>[Data Field]</b></p>

	<p><b>\$PAIR065*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li><b>PAIR_ACK</b> for send result.</li> <li><b>\$PAIR065,&lt;HaccMask&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></li> </ol> <p>HaccMask:</p> <p>30~200: enable hacc mask feature. (Units: meter)</p> <p>0 [Default Value]: disable hacc mask feature.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR065*39\r\n</p> <p>Response:</p> <p>\$PAIR001,065,0*38\r\n ==&gt; Success</p> <p>\$PAIR065,50*10\r\n</p> </div>
<p>PAIR_COMMON_SE T_GNSS_SEARCH_M ODE</p>	<p><b>[Packet Type]</b></p> <p>066</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_GNSS_SEARCH_MODE</p> <p><b>[Description]</b></p> <p>Configure the receiver to start searching for satellites. The setting is available when the NVRAM data is valid.</p> <p>The device restarts when it receives this command.</p> <p>Abbreviation: (GPS: "G", GLONASS: "R", Galileo: "E", BeiDou: "B", NavIC, "I")</p> <p>Support constellation in L1 package: G/ GR/ GE/ GB/ GREB</p> <p>Support constellation in L1 + L5 package: GREB / GEB</p> <p>Support constellation in L1 + NavIC package G/ I/ GEI/ GREB/ GREBI</p> <p>QZSS is always switchable.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR066,&lt;GPS_Enabled&gt;,&lt;GLONASS_Enabled&gt;,&lt;Galileo_Enabled&gt;,&lt;BeiDou_Enabled&gt; ,&lt;QZSS_Enabled&gt;,&lt;NavIC_Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>GPS_Enabled:</p> <p>"0", disable (DO NOT search GPS satellites).</p> <p>"1", search GPS satellites.</p> <p>GLONASS_Enabled:</p> <p>"0", disable (DO NOT search GLONASS satellites).</p> <p>"1", search GLONASS satellites.</p> <p>Galileo_Enabled:</p> <p>"0", disable (DO NOT search Galileo satellites).</p>

	<p>"1", search Galileo satellites. BeiDou_Enabled: "0", disable (DO NOT search BeiDou satellites). "1", search BeiDou satellites. QZSS_Enabled: "0", disable (DO NOT search QZSS satellites). "1", search QZSS satellites. NavIC_Enabled: "0", disable (DO NOT search NavIC satellites). "1", search NavIC satellites.</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR066,1,0,0,0,0*3B\r\n ==&gt; Search GPS satellites only.</p> <p>Response: \$PAIR001,066,0*3B\r\n ==&gt; Success</p> <p>Send: \$PAIR066,1,1,1,1,0*3B\r\n ==&gt; Search GPS, GLONASS, Galileo, BeiDou, QZSS satellites.</p> <p>Response: \$PAIR001,066,0*3B\r\n ==&gt; Success</p> <p>Send: \$PAIR066,1,1,0,0,0*3A\r\n ==&gt; Search GPS and GLONASS satellites.</p> <p>Response: \$PAIR001,066,0*3B\r\n ==&gt; Success</p> </div>
<p>PAIR_COMMON_GE T_GNSS_SEARCH_M ODE</p>	<p><b>[Packet Type]</b></p> <p>067</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_GNSS_SEARCH_MODE</p> <p><b>[Description]</b></p> <p>This command is to get GPS, GLONASS, Galileo, BeiDou, QZSS and NavIC search settings.</p> <p><b>[Data Field]</b></p> <p>\$PAIR067*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>PAIR067,&lt;GPS_Enabled&gt;,&lt;GLONASS_Enabled&gt;,&lt;Galileo_Enabled&gt;,&lt;BeiDou_Enabled&gt;,&lt;QZSS_Enabled&gt;,&lt;NavIC_Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p>

	<p>GPS_Enabled: "0", disable (DO NOT search GPS satellites). "1", search GPS satellites.</p> <p>GLONASS_Enabled: "0", disable (DO NOT search GLONASS satellites). "1", search GLONASS satellites.</p> <p>Galileo_Enabled: "0", disable (DO NOT search Galileo satellites). "1", search Galileo satellites.</p> <p>BeiDou_Enabled: "0", disable (DO NOT search BeiDou satellites). "1", search BeiDou satellites.</p> <p>QZSS_Enabled: "0", disable (DO NOT search QZSS satellites). "1", search QZSS satellites.</p> <p>NavIC_Enabled: "0", disable (DO NOT search NavIC satellites). "1", search NavIC satellites.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR067*3B\r\n</p> <p>Response: \$PAIR001,067,0*3A\r\n ==&gt; Success \$PAIR067,1,0,0,0,0*3A\r\n ==&gt; Search GPS satellites only.</p> </div>
<p>PAIR_COMMON_SE T_HDOP_THRESHOLD</p>	<p><b>[Packet Type]</b> 068</p> <p><b>[Command]</b> PAIR_COMMON_SET_HDOP_THRESHOLD</p> <p><b>[Description]</b> This command is for setting the HDOP threshold. If the HDOP value is larger than this threshold value, the position will not be fixed.</p> <p><b>[Data Field]</b> \$PAIR068,&lt;HDOPThreshold&gt;*CS&lt;CR&gt;&lt;LF&gt; HDOPThreshold: "0": Disable this function. Other value: Enable setting the HDOP threshold [Range: ]</p> <p><b>[Return]</b></p>

	<p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 40px;">\$PAIR068,0.8*3E\r\n</p> <p>Response:</p> <p style="padding-left: 40px;">\$PAIR001,068,0*35\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GET_HDOP_THRESHOLD	<p><b>[Packet Type]</b></p> <p>069</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_HDOP_THRESHOLD</p> <p><b>[Description]</b></p> <p>This command is to get the HDOP threshold.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR069*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR069,&lt;HDOPThreshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>HDOPThreshold:</p> <p>"0": Disable this function.</p> <p>Other value: Enable setting the HDOP threshold [Range: ]</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 40px;">\$PAIR069*35\r\n</p> <p>Response:</p> <p style="padding-left: 40px;">\$PAIR001,069,0*34\r\n ==&gt; Success</p> <p style="padding-left: 40px;">\$PAIR069,0.8*3F\r\n</p> </div>
PAIR_COMMON_SET_STATIC_THRESHOLD	<p><b>[Packet Type]</b></p> <p>070</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_STATIC_THRESHOLD</p> <p><b>[Description]</b></p> <p>Set the speed threshold for static navigation.</p> <p>If the actual speed is less than the threshold, the output position remains the same and the output speed will be zero.</p> <p>If the threshold value is set to 0, this function is disabled.</p> <p><b>[Data Field]</b></p>



	<p><b>\$PAIR070,&lt;Speed_threshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Speed_threshold. 0~20 dm/s. Default value is 0 dm/s. The minimum is 1 dm/s, the maximum is 20 dm/s. 1 dm/s = 0.1m/s</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR070,4*25\r\n</p> <p>Response: \$PAIR001,070,0*3C\r\n ==&gt; Success</p> </div>
<p>PAIR_COMMON_GET_STATIC_THRESHOLD OLD</p>	<p><b>[Packet Type]</b></p> <p>071</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_STATIC_THRESHOLD</p> <p><b>[Description]</b></p> <p>Query the static navigation speed threshold.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR071*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR071,&lt;Speed_threshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Speed_threshold. 0~2 m/s. Default value is 0 m/s. The minimum is 0.1 m/s, the maximum is 2.0 m/s.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR071*3C\r\n</p> <p>Response: \$PAIR001,071,0*3D\r\n ==&gt; Success \$PAIR071,0.4*3A\r\n</p> </div>
<p>PAIR_COMMON_SET_ELEV_MASK</p>	<p><b>[Packet Type]</b></p> <p>072</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_ELEV_MASK</p> <p><b>[Description]</b></p> <p>Set satellite elevation mask.</p>

	<p>Satellites below the elevation mask are not used.</p> <p><b>[Data Field]</b></p> <p>\$PAIR072,&lt;Degree&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Degree: Satellite elevation-mask. (Valid range: -90 ~ 90, default value: 5)</p> <p><b>[Return]</b></p> <p>1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR072,5*26\r\n</p> <p>Response:</p> <p>\$PAIR001,072,0*3E\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GET_ELEV_MASK	<p><b>[Packet Type]</b></p> <p>073</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_ELEV_MASK</p> <p><b>[Description]</b></p> <p>Get satellite elevation mask.</p> <p><b>[Data Field]</b></p> <p>\$PAIR073*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. PAIR_ACK for send result.</p> <p>2. \$PAIR073,&lt;Degree&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Degree: Satellite elevation-mask. (Valid range: -90 ~ 90, default value: 5)</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR073*3E\r\n</p> <p>Response:</p> <p>\$PAIR001,073,0*3F\r\n ==&gt; Success</p> <p>\$PAIR073,5*27\r\n</p> </div>
PAIR_COMMON_SET_AIC_ENABLE	<p><b>[Packet Type]</b></p> <p>074</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_AIC_ENABLE</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by PAIR_GNSS_SUBSYS_GET_STATUS.</p>

	<p><b>[Description]</b></p> <p>Enable or disable active interference cancellation function.</p> <p><b>[Data Field]</b></p> <p>\$PAIR074,&lt;Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enabled. Enable or disable</p> <p>"0", Disable.</p> <p>"1", Enable.</p> <p><b>[Return]</b></p> <p>1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR074,1*24\r\n</p> <p>Response:</p> <p>\$PAIR001,074,0*38\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GET_AIC_STATUS	<p><b>[Packet Type]</b></p> <p>075</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_AIC_STATUS</p> <p><b>[Description]</b></p> <p>Get the status of active interference cancellation function.</p> <p><b>[Data Field]</b></p> <p>\$PAIR075*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. PAIR_ACK for send result.</p> <p>2. \$PAIR075,&lt;Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enabled: Enable or disable</p> <p>"0", Disable.</p> <p>"1", Enable.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR075*38\r\n</p> <p>Response:</p> <p>\$PAIR001,075,0*39\r\n ==&gt; Success</p> <p>\$PAIR075,0*24\r\n ==&gt; AIC is disabled.</p> </div>
PAIR_COMMON_SE_T_DATUM	<p><b>[Packet Type]</b></p> <p>076</p>

	<p><b>[Command]</b> PAIR_COMMON_SET_DATUM</p> <p><b>[Description]</b> Set default datum.</p> <p><b>[Data Field]</b> \$PAIR076,&lt;Datum&gt;*CS&lt;CR&gt;&lt;LF&gt; Datum: 0: WGS84 1: TOKYO-M 2: TOKYO-A ...</p> <p><b>[Return]</b> 1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR076,0*27\r\n</p> <p>Response: \$PAIR001,076,0*3A\r\n ==&gt; Success</p> </div> <p><b>[Note]</b> The total datums list in the <a href="#">Appendix - Datum List</a>.</p>
<p>PAIR_COMMON_GET_DATUM</p>	<p><b>[Packet Type]</b> 077</p> <p><b>[Command]</b> PAIR_COMMON_GET_DATUM</p> <p><b>[Description]</b> Get default datum.</p> <p><b>[Data Field]</b> \$PAIR077*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. PAIR_ACK for send result. 2. \$PAIR077,&lt;Datum&gt;*CS&lt;CR&gt;&lt;LF&gt; Datum: 0: WGS84 1: TOKYO-M 2: TOKYO-A The total datums list in the <a href="#">Appendix - Datum List</a>.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> </div>

	<pre>\$PAIR077*3A\r\n Response: \$PAIR001,077,0*3B\r\n ==&gt; Success \$PAIR077,0*26\r\n</pre>
PAIR_COMMON_SE T_NAVIGATION_MO DE	<p><b>[Packet Type]</b> 080</p> <p><b>[Command]</b> PAIR_COMMON_SET_NAVIGATION_MODE</p> <p><b>[Description]</b> Set navigation mode. The command fails in the following situations: if ULP is enabled, it fails to set Non Fitness mode. if the current RF LNA gain is "High gain", only Normal mode and Drone mode can be configured. all detailed failure information will be displayed in system log.</p> <p><b>[Data Field]</b> <b>\$PAIR080,&lt;CmdType&gt;*CS&lt;CR&gt;&lt;LF&gt;</b> CmdType:                  '0' Normal mode: For general purpose                  '1' [Default Value] Fitness mode: For running and walking activities so that the low-speed (&lt; 5 m/s) movement will have more of an effect on the position calculation.                  '2' Reserved                  '3' Balloon mode: For high-altitude balloon purpose that the vertical movement will have more effect on the position calculation.                  '4' Stationary mode: For stationary applications where a zero dynamic assumed.                  '5' Drone mode: Used for drone applications with equivalent dynamics range and vertical acceleration on different flight phase. (Ex. hovering, cruising, etc.).                  (Note: The NMEA decimal precision will change to lat/lon in 7 digits, alt in 3 digit automaully)                  '6' Reserved                  '7' Swimming mode: For swimming purpose so that it smooths the trajectory and improves the accuracy of distance calculation.</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <pre>Send: \$PAIR080,1*2F\r\n ==&gt; Enter fitness mode. Response: \$PAIR001,080,0*33\r\n ==&gt; Success</pre>

	<p><b>[Note]</b></p> <p>Each mode has its altitude limitation.</p> <p>Please choose the appropriate mode based on the following table.</p> <p>If your test scenario exceeds the limitation, the position calculation will be incorrect.</p> <table border="1"> <thead> <tr> <th>Mode</th> <th>Altitude Limitation</th> </tr> </thead> <tbody> <tr> <td>Normal mode</td> <td>10000 m</td> </tr> <tr> <td>Fitness mode</td> <td>10000 m</td> </tr> <tr> <td>Balloon mode</td> <td>80000 m</td> </tr> <tr> <td>Stationary mode</td> <td>10000 m</td> </tr> <tr> <td>Drone mode</td> <td>10000 m</td> </tr> <tr> <td>Swimming mode</td> <td>10000 m</td> </tr> </tbody> </table>	Mode	Altitude Limitation	Normal mode	10000 m	Fitness mode	10000 m	Balloon mode	80000 m	Stationary mode	10000 m	Drone mode	10000 m	Swimming mode	10000 m
Mode	Altitude Limitation														
Normal mode	10000 m														
Fitness mode	10000 m														
Balloon mode	80000 m														
Stationary mode	10000 m														
Drone mode	10000 m														
Swimming mode	10000 m														
PAIR_COMMON_GET_NAVIGATION_MODE	<p><b>[Packet Type]</b></p> <p>081</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_NAVIGATION_MODE</p> <p><b>[Description]</b></p> <p>Get navigation mode.</p> <p><b>[Data Field]</b></p> <p>\$PAIR081*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. PAIR_ACK for send result.</li> <li>2. \$PAIR081,&lt;CmdType&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>CmdType:</p> <ul style="list-style-type: none"> <li>'0' Normal mode: For general purpose</li> <li>'1' [Default Value] Fitness mode: For running and walking activities so that the low-speed (&lt; 5 m/s) movement will have more of an effect on the position calculation.</li> <li>'2' Reserved</li> <li>'3' Balloon mode: For high-altitude balloon purpose that the vertical movement will have more effect on the position calculation.</li> <li>'4' Stationary mode: For stationary applications where a zero dynamic assumed.</li> <li>'5' Drone mode: Used for drone applications with equivalent dynamics range and vertical acceleration on different flight phase. (Ex. hovering, cruising, etc.)</li> </ul> <p>(Note: The precision of NMEA automatically changes to 7 decimal places for latitude/longitude, and 3 decimal places for altitude.)</p> <ul style="list-style-type: none"> <li>'6' Reserved</li> <li>'7' Swimming mode: For swimming purpose so that it smooths the trajectory and improves the accuracy of distance calculation.</li> </ul> <p><b>[Example]</b></p>														

	<p>Send:</p> <p>\$PAIR081*33\r\n</p> <p>Response:</p> <p>\$PAIR001,081,0*32\r\n ==&gt; Success</p> <p>\$PAIR081,1*2E\r\n ==&gt; Current is fitness mode.</p>
PAIR_COMMON_SE T_DEBUGLOG_OUT PUT	<p><b>[Packet Type]</b></p> <p>086</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_DEBUGLOG_OUTPUT</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b></p> <p>This command is to set enable/disable debug log output in binary format</p> <p><b>[Data Field]</b></p> <p>\$PAIR086,&lt;Status&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Status:</p> <p>0: Disable</p> <p>1: Enable with full debuglog output</p> <p>2: Enable with lite debuglog output</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <p>\$PAIR086,1*29\r\n</p> <p>Response:</p> <p>\$PAIR001,086,0*35\r\n ==&gt; Success</p>
PAIR_COMMON_GE T_DEBUGLOG_OUT PUT	<p><b>[Packet Type]</b></p> <p>087</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_DEBUGLOG_OUTPUT</p> <p><b>[Description]</b></p> <p>Query setting of debug log output.</p> <p><b>[Data Field]</b></p> <p>\$PAIR087*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p>



	<p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR087,&lt;Status&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Status:</p> <p>0: Disable</p> <p>1: Enable with full debuglog output</p> <p>2: Enable with lite debuglog output</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR087*35\r\n</pre> <p>Response:</p> <pre>\$PAIR001,087,0*34\r\n ==&gt; Success</pre> <pre>\$PAIR087,1*28 ==&gt; Enable with full debuglog output</pre>
PAIR_COMMON_SE T_STATIC_MODE	<p><b>[Packet Type]</b></p> <p>092</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_STATIC_MODE</p> <p><b>[Description]</b></p> <p>Enable static mode</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR092,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Enable:</p> <p>0: Disable static mode</p> <p>1: Enable static mode</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR092,1*2C\r\n</pre> <p>Response:</p> <pre>\$PAIR001,092,0*30\r\n ==&gt; Success</pre>
PAIR_COMMON_GE T_STATIC_MODE	<p><b>[Packet Type]</b></p> <p>093</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_STATIC_MODE</p> <p><b>[Description]</b></p> <p>Query if current mode is static mode</p>

	<p><b>[Data Field]</b>  <b>\$PAIR093*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li><b>PAIR_ACK</b> for send result.</li> <li><b>\$PAIR093,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></li> </ol> <p>Enable:</p> <p>0: Not in static mode</p> <p>1: In static mode</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                  \$PAIR093*30\r\n</p> <p>Response:                  \$PAIR001,093,0*31\r\n ==&gt; Success                  \$PAIR093,1*2D\r\n ==&gt; In static mode</p> </div>
PAIR_COMMON_SE T_NMEA_POS_DECI MAL_PRECISION	<p><b>[Packet Type]</b>                  098</p> <p><b>[Command]</b>                  PAIR_COMMON_SET_NMEA_POS_DECIMAL_PRECISION</p> <p><b>[Description]</b>                  This command is for setting the digits shown in the NMEA position.</p> <p><b>[Data Field]</b>  <b>\$PAIR098,&lt;MODE&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>MODE:</p> <p>0: Latitude, Longitude in 4 digits, Altitude in 1 digit</p> <p>1: Latitude, Longitude in 5 digits, Altitude in 2 digit</p> <p>2: Latitude, Longitude in 6 digits, Altitude in 3 digit</p> <p>3: Latitude, Longitude in 7 digits, Altitude in 3 digit</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li><b>PAIR_ACK</b> for send result.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                  \$PAIR098,0*27\r\n                  ==&gt; Set the Lat/Lon digit 4 digit, and Alt in 1 digit (GGA/GLL/RMC)</p> <p>Response:                  \$PAIR001,098,0*3A\r\n ==&gt; Success</p> </div>
PAIR_COMMON_GE	<p><b>[Packet Type]</b></p>

<p>T_NMEA_POS_DECIMAL_PRECISION</p>	<p>099</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_NMEA_POS_DECIMAL_PRECISION</p> <p><b>[Description]</b></p> <p>This command is to get NMEA position shown digit mode</p> <p><b>[Data Field]</b></p> <p>\$PAIR099*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. PAIR_ACK for send result.</li> <li>2. \$PAIR099,&lt;MODE&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>MODE:</p> <p>0: Latitude, Longitude in 4 digits, Altitude in 1 digit</p> <p>1: Latitude, Longitude in 5 digits, Altitude in 2 digit</p> <p>2: Latitude, Longitude in 6 digits, Altitude in 3 digit</p> <p>3: Latitude, Longitude in 7 digits, Altitude in 3 digit</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR099*3A\r\n</p> <p>Response:</p> <p>\$PAIR001,099,0*3B\r\n ==&gt; Success</p> <p>\$PAIR099,0*26\r\n ==&gt; Latitude, Longitude in 4 digits, Altitude in 1 digit</p> </div>
<p>PAIR_COMMON_SET_NMEA_OUTPUT_MODE</p>	<p><b>[Packet Type]</b></p> <p>100</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_NMEA_OUTPUT_MODE</p> <p><b>[Description]</b></p> <p>This command is to set NMEA output mode</p> <p><b>[Data Field]</b></p> <p>\$PAIR100,&lt;NMEA_MODE&gt;,&lt;PROPRIETARY_MODE&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>NMEA_MODE:</p> <p>0: Disable NMEA</p> <p>1: ASCII NMEA v4.10(Default)</p> <p>2: ASCII NMEA v3.0</p> <p>3: ASCII NMEA v4.11</p> <p>PROPRIETARY_MODE:</p> <p>0: Disable extra proprietary sentence (Default)</p> <p>1: Enable proprietary sentence</p>

	<p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send: \$PAIR100,1,0*3A\r\n ==&gt; ASCII NMEA v4.10, Disable extra proprietary sentence</p> <p>Response: \$PAIR001,100,0*3A\r\n ==&gt; Success</p> <p>Send: \$PAIR100,0,1*3A\r\n ==&gt; No ASCII NMEA output, Enable proprietary sentence</p> <p>Response: \$PAIR001,100,0*3A\r\n ==&gt; Success</p>
<p>PAIR_COMMON_GET_NMEA_OUTPUT_MODE</p>	<p><b>[Packet Type]</b></p> <p>101</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_NMEA_OUTPUT_MODE</p> <p><b>[Description]</b></p> <p>This command is to get NMEA output mode</p> <p><b>[Data Field]</b></p> <p>\$PAIR101*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. \$PAIR101,&lt;NMEA_MODE&gt;,&lt;PROPRIETARY_MODE&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>NMEA_MODE:</p> <p>0: Disable NMEA</p> <p>1: ASCII NMEA v4.10(Default)</p> <p>2: ASCII NMEA v3.0</p> <p>3: ASCII NMEA v4.11</p> <p>PROPRIETARY_MODE:</p> <p>0: Disable extra proprietary sentence (Default)</p> <p>1: Enable proprietary sentence</p> <p>2: Enable proprietary sentence and output before NMEA</p> <p><b>[Example]</b></p> <p>Send: \$PAIR101*3A\r\n</p> <p>Response: \$PAIR001,101,0*3B\r\n ==&gt; Success</p> <p>\$PAIR101,0,1*3B\r\n ==&gt; Disable NMEA output, enable proprietary sentence</p>

PAIR_COMMON_SE T_SV_BLACKLIST	<p><b>[Packet Type]</b> 130</p> <p><b>[Command]</b> PAIR_COMMON_SET_SV_BLACKLIST</p> <p><b>[Note]</b> This configuration will not keep in the flash or RTC RAM. Please send this command every time after the GNSS subsystem or main power reboots. This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b> Set sv blacklist for selected constellation, which excludes specific PRNs and does not search for them.</p> <p><b>[Data Field]</b> \$PAIR130,&lt;System_ID&gt;,&lt;Blacklist&gt;*CS&lt;CR&gt;&lt;LF&gt; System_ID: The GNSS constellation 0: GPS L1/L5 1: GLONASS L1 2: Galileo E1/E5a 3: BeiDou B1/B2a 4: QZSS L1/L5 5: NavIC L5 Blacklist: Bitwise format in HEX (LSB for QZSS NMEA PRN: 193, GLONASS NMEA PRN: 65, others PRN: 1)</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;">                 Send:                  \$PAIR130,0,8000C001*72\r\n ==&gt; Disable tracking GPS PRN 1,15,16,32                  Response:                  \$PAIR001,130,0*39\r\n ==&gt; Success             </div>
PAIR_COMMON_GE T_SV_BLACKLIST	<p><b>[Packet Type]</b> 131</p> <p><b>[Command]</b> PAIR_COMMON_GET_SV_BLACKLIST</p> <p><b>[Note]</b> This command will get a failed response if GNSS-SubSys does not power on. You can get the</p>

	<p>GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b></p> <p>Get sv blacklist for selected constellation, which excludes specific PRNs and does not search for them.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR131,&lt;System_ID&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>System_ID: The GNSS constellation</p> <p>0: GPS L1/L5</p> <p>1: GLONASS L1</p> <p>2: Galileo E1/E5a</p> <p>3: BeiDou B1/B2a</p> <p>4: QZSS L1/L5</p> <p>5: NavIC L5</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR131,&lt;System_ID&gt;,&lt;Blacklist&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>System_ID: The GNSS constellation</p> <p>0: GPS L1/L5</p> <p>1: GLONASS L1</p> <p>2: Galileo E1/E5a</p> <p>3: BeiDou B1/B2a</p> <p>4: QZSS L1/L5</p> <p>5: NavIC L5</p> <p>Blacklist: Bitwise format in HEX</p> <p>(LSB for QZSS NMEA PRN: 193, GLONASS NMEA PRN: 65, others PRN: 1)</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR131,0*25\r\n</p> <p>Response:</p> <p>\$PAIR001,131,0*38\r\n ==&gt; Success</p> <p>\$PAIR131,0,8000C001*73\r\n ==&gt; Disable tracking GPS PRN 1,15,16,32</p> </div>
<p>PAIR_COMMON_SE T_STATIC_THRESH OLD_ADVANCE</p>	<p><b>[Packet Type]</b></p> <p>144</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_STATIC_THRESHOLD_ADVANCE</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the</p>

	<p>GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b></p> <p>Set the position difference threshold for static navigation.</p> <p>If the actual position difference is less than the threshold and, at the same time, the speed is less than the threshold set from PAIR_COMMON_SET_STATIC_THRESHOLD(PAIR070), the output position is remains the same and the output speed is zero. STATIONARY and DRONE modes do not support this command.</p> <p><b>[Data Field]</b></p> <p>\$PAIR144,&lt;Pos_Diff_threshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Pos_Diff_threshold: 10~60 mter. Default value is 10 meter.</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR144,20*15\r\n</p> <p>Response:</p> <p>\$PAIR001,144,0*3A\r\n ==&gt; Success</p> </div>
<p>PAIR_COMMON_GET_STATIC_THRESHOLD_ADVANCE</p>	<p><b>[Packet Type]</b></p> <p>145</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_STATIC_THRESHOLD_ADVANCE</p> <p><b>[Description]</b></p> <p>Query the static navigation position difference threshold.</p> <p><b>[Data Field]</b></p> <p>\$PAIR145*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR_ACK</a> for send result.</p> <p>2. \$PAIR145,&lt;Pos_Diff_threshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Pos_Diff_threshold: 10~60 mter. Default value is 10 meter.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR145*3A\r\n</p> <p>Response:</p> <p>\$PAIR001,145,0*3B\r\n ==&gt; Success</p> <p>\$PAIR145,20.0*0A\r\n</p> </div>

PAIR_COMMON_SE T_RLM_OUTPUT_EN ABLE	<p><b>[Packet Type]</b> 154</p> <p><b>[Command]</b> PAIR_COMMON_SET_RLM_OUTPUT_ENABLE</p> <p><b>[Description]</b> Enable to output Return Link Message from navigation data.</p> <p><b>[Data Field]</b> \$PAIR154,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt; Enable: 0: Disable 1: Enable</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;">                 Send:                  \$PAIR154,1*27\r\n                  Response:                  \$PAIR001,154,0*3B\r\n ==&gt; Success             </div>
PAIR_COMMON_GE T_RLM_OUTPUT_ST ATUS	<p><b>[Packet Type]</b> 155</p> <p><b>[Command]</b> PAIR_COMMON_GET_RLM_OUTPUT_STATUS</p> <p><b>[Description]</b> Query output Return Link Message status.</p> <p><b>[Data Field]</b> \$PAIR155*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result. 2. \$PAIR155,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt; Enable: 0: Disable 1: Enable</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;">                 Send:                  \$PAIR155*3B\r\n                  Response:                  \$PAIR001,155,0*3A\r\n ==&gt; Success             </div>



	<pre>\$PAIR155,1*26\r\n</pre>
PAIR_COMMON_SE T_B1C_ENABLE	<p><b>[Packet Type]</b> 158</p> <p><b>[Command]</b> PAIR_COMMON_SET_B1C_ENABLE</p> <p><b>[Description]</b> Enable B1c.</p> <p><b>[Data Field]</b>  <pre>\$PAIR158,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</pre>                     Enable:                      0: Disable                      1: Enable                 </p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:  <pre>\$PAIR158,1*2B\r\n</pre>                     Response:  <pre>\$PAIR001,158,0*37\r\n ==&gt; Success</pre> </p></div>
PAIR_COMMON_GE T_B1C_STATUS	<p><b>[Packet Type]</b> 159</p> <p><b>[Command]</b> PAIR_COMMON_GET_B1C_STATUS</p> <p><b>[Description]</b> Query output B1c enable status.</p> <p><b>[Data Field]</b>  <pre>\$PAIR159*CS&lt;CR&gt;&lt;LF&gt;</pre> </p> <p><b>[Return]</b>                      1. <b>PAIR_ACK</b> for send result.                      2. <pre>\$PAIR159,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</pre>                     Enable:                      0: Disable                      1: Enable                 </p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:  <pre>\$PAIR159*37\r\n</pre> </p></div>

	Response: \$PAIR001,159,0*36\r\n ==> Success \$PAIR159,1*2A\r\n
PAIR_COMMON_SE T_IMMEDIATE_SPE ED_MODE	<p><b>[Packet Type]</b> 160</p> <p><b>[Command]</b> PAIR_COMMON_SET_IMMEDIATE_SPEED_MODE</p> <p><b>[Description]</b>                      Enable immediate speed mode.                      This mode results in greater acceleration and less smoothing of speed than normal mode.                      This mode is currently only supported with normal mode. The default setting is disabled.</p> <p><b>[Data Field]</b>  <b>\$PAIR160,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>                      Enable:                      0: Disable [Default]                      1: Enable</p> <p><b>[Return]</b>                      1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;">                     Send:                      \$PAIR160,1*20\r\n ==&gt; Enabl immediate speed mode                      Response:                      \$PAIR001,160,0*3C\r\n ==&gt; Success                 </div>
PAIR_COMMON_GE T_IMMEDIATE_SPE ED_MODE	<p><b>[Packet Type]</b> 161</p> <p><b>[Command]</b> PAIR_COMMON_GET_IMMEDIATE_SPEED_MODE</p> <p><b>[Description]</b> Query if immediate speed mode is enabled.</p> <p><b>[Data Field]</b> <b>\$PAIR161*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b>                      1. <b>PAIR_ACK</b> for send result.                      2. <b>\$PAIR161,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>                      Enable:                      0: Disable</p>

	<p>1: Enable</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR161*3C\r\n</pre> <p>Response:</p> <pre>\$PAIR001,161,0*3D\r\n ==&gt; Success</pre> <pre>\$PAIR161,0*20\r\n ==&gt; immediate speed mode is disabled</pre>
<p>PAIR_COMMON_SE T_2D_FIX_ENABLE</p>	<p><b>[Packet Type]</b></p> <p>162</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_2D_FIX_ENABLE</p> <p><b>[Description]</b></p> <p>Enable 2D fix mode.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR162,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Enable:</p> <p>0: Disable [Default]</p> <p>1: Enable</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR ACK</a> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR162,1*22\r\n ==&gt; Enabl immediate speed mode</pre> <p>Response:</p> <pre>\$PAIR001,162,0*3E\r\n ==&gt; Success</pre>
<p>PAIR_COMMON_GE T_2D_FIX_ENABLE</p>	<p><b>[Packet Type]</b></p> <p>163</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_2D_FIX_ENABLE</p> <p><b>[Description]</b></p> <p>Query if 2D fix mode is enabled.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR163*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR ACK</a> for sending result.</p> <p>2. <b>\$PAIR163,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Enable:</p>

	<p>0: Disable 1: Enable</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR163*3E\r\n</pre> <p>Response:</p> <pre>\$PAIR001,163,0*3F\r\n ==&gt; Success \$PAIR163,0*22\r\n ==&gt; 2D fix mode is disabled</pre>
PAIR_COMMON_SET_ODOMETER_ENABLE	<p><b>[Packet Type]</b></p> <p>164</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_SET_ODOMETER_ENABLE</p> <p><b>[Description]</b></p> <p>Enable the odometer function. STATIONARY mode does not support this command.</p> <p><b>[Data Field]</b></p> <p>\$PAIR164,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable:</p> <p>0: Disable [Default] 1: Enable</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR164,1*24\r\n ==&gt; Enable the odometer function.</pre> <p>Response:</p> <pre>\$PAIR001,164,0*38\r\n ==&gt; Success</pre>
PAIR_COMMON_GET_ODOMETER_STATUS	<p><b>[Packet Type]</b></p> <p>165</p> <p><b>[Command]</b></p> <p>PAIR_COMMON_GET_ODOMETER_STATUS</p> <p><b>[Description]</b></p> <p>Query the status of the odometer function and the traveling distance value if the function is enabled.</p> <p><b>[Data Field]</b></p> <p>\$PAIR165*CS&lt;CR&gt;&lt;LF&gt;</p>

	<p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR165,&lt;Enable&gt;,&lt;distance&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>            Enable:            0: Disable            1: Enable            distance:            This is the traveling distance, which is ranged from 0.0m to 268,435,455.0m, since the epoch when the function is enabled.            If the distance exceeds the max. value, the distance will be rolled over to 0.0m and then accumulated again.            When the odometer function is disabled and then enabled again, the distance will be restarted from 0.0m.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:            \$PAIR165*38\r\n ==&gt; Enable the odometer function.</p> <p>Response:            \$PAIR001,165,0*39\r\n ==&gt; Success            \$PAIR165,0,0.0*26\r\n</p> </div>
<p>PAIR_DGPS_SET_MODE</p>	<p><b>[Packet Type]</b> 400</p> <p><b>[Command]</b> PAIR_DGPS_SET_MODE</p> <p><b>[Description]</b> DGPS correction data source mode.</p> <p><b>[Data Field]</b>  <b>\$PMTK400,&lt;Mode&gt; *CS&lt;CR&gt;&lt;LF&gt;</b>            Mode: DGPS data source mode.            '0': No DGPS source            '1': RTCM            '2': SBAS(Include WAAS/EGNOS/GAGAN/MSAS)            '3': SLAS</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:            \$PAIR400,2*20\r\n ==&gt; Set SBAS Mode</p> </div>

	Response: \$PAIR001,400,0*3F\r\n ==> Success
PAIR_DGPS_GET_M ODE	<p><b>[Packet Type]</b> 401</p> <p><b>[Command]</b> PAIR_DGPS_GET_MODE</p> <p><b>[Description]</b> Query the DGPS data source mode.</p> <p><b>[Data Field]</b> \$PAIR401*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. \$PAIR401,&lt;Mode&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>Mode: DGPS data source mode.</p> <ul style="list-style-type: none"> <li>'0': No DGPS source</li> <li>'1': RTCM</li> <li>'2': SBAS(Include WAAS/EGNOS/GAGAN/MSAS)</li> <li>'3': SLAS</li> </ul> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;">                 Send:                  \$PAIR401*3F\r\n             </div> <p>Response:                  \$PAIR001,401,0*3E\r\n ==&gt; Success                  \$PAIR401,2*21\r\n ==&gt; SBAS Mode             </p>
PAIR_SBAS_ENABL E	<p><b>[Packet Type]</b> 410</p> <p><b>[Command]</b> PAIR_SBAS_ENABLE</p> <p><b>[Description]</b> Enable searching a SBAS satellite or not. When navigation mode is Fitness or Swimming mode, SBAS is not supported.</p> <p><b>[Data Field]</b> \$PAIR410,&lt;Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enabled: Enable or disable</p> <ul style="list-style-type: none"> <li>'0' = Disable</li> <li>'1' = Enable</li> </ul>

	<p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> </ol> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR410,1*22\r\n ==&gt; Enable SBAS</pre> <p>Response:</p> <pre>\$PAIR001,410,0*3E\r\n ==&gt; Success</pre>
PAIR_SBAS_GET_STATUS	<p><b>[Packet Type]</b></p> <p>411</p> <p><b>[Command]</b></p> <p>PAIR_SBAS_GET_STATUS</p> <p><b>[Description]</b></p> <p>Query the status of SBAS to whether it is enabled.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR411*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR411,&lt;Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></li> </ol> <p>Enabled: Enable or disable</p> <p>'0' = Disable</p> <p>'1' = Enable</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR411*3E\r\n</pre> <p>Response:</p> <pre>\$PAIR001,411,0*3F\r\n ==&gt; Success</pre> <pre>\$PAIR411,1*23\r\n ==&gt; Enable SBAS</pre>
PAIR_SBAS_GET_SAT_INFO	<p><b>[Packet Type]</b></p> <p>412</p> <p><b>[Command]</b></p> <p>PAIR_SBAS_GET_SAT_INFO</p> <p><b>[Description]</b></p> <p>Get information about the SBAS satellites, such as SVid, SNR, azimuth, and elevation.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR412*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p>

	<p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR412,&lt;SVid&gt;,&lt;SNR&gt;,&lt;Azim&gt;,&lt;Elev&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Example]</b></p> <p>Send:</p> <p style="padding-left: 40px;"><b>\$PAIR412*3D\r\n</b></p> <p>Response:</p> <p style="padding-left: 40px;"><b>\$PAIR001,412,0*3C\r\n ==&gt; Success</b></p> <p style="padding-left: 40px;"><b>\$PAIR412,50,42,134,50*0D\r\n</b></p>
PAIR_SLAS_ENABLE	<p><b>[Packet Type]</b></p> <p style="padding-left: 40px;">420</p> <p><b>[Command]</b></p> <p style="padding-left: 40px;">PAIR_SLAS_ENABLE</p> <p><b>[Description]</b></p> <p style="padding-left: 40px;">Enable the QZSS SLAS (Sub-meter Level Augmentation Service) operation.</p> <p><b>[Data Field]</b></p> <p style="padding-left: 40px;"><b>\$PAIR420,&lt;Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p style="padding-left: 40px;">Enabled: Enable or disable</p> <p style="padding-left: 40px;">'0' = Disable</p> <p style="padding-left: 40px;">'1' = Enable</p> <p><b>[Return]</b></p> <p style="padding-left: 40px;">1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <p style="padding-left: 40px;"><b>\$PAIR420,1*21\0d\0a ==&gt; Enable QZSS SLAS</b></p> <p>Response:</p> <p style="padding-left: 40px;"><b>\$PAIR001,420,0*3D\0d\0a ==&gt; Success</b></p>
PAIR_SLAS_GET_STATUS	<p><b>[Packet Type]</b></p> <p style="padding-left: 40px;">421</p> <p><b>[Command]</b></p> <p style="padding-left: 40px;">PAIR_SLAS_GET_STATUS</p> <p><b>[Description]</b></p> <p style="padding-left: 40px;">Query the status of SLAS to check whether it is enabled.</p> <p><b>[Data Field]</b></p> <p style="padding-left: 40px;"><b>\$PAIR421*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p style="padding-left: 40px;">1. <b>PAIR_ACK</b> for send result.</p> <p style="padding-left: 40px;">2. <b>\$PAIR421,&lt;Enabled&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p>



	<p>Enabled: Enable or disable                  '0' = Disable                  '1' = Enable</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR421*3D\0d\0a</p> <p>Response:                      \$PAIR001,421,0*3C\0d\0a ==&gt; Success                      \$PAIR421,1*20\0d\0a ==&gt; The status of QZSS SLAS is enabled</p> </div>
PAIR_RTCM_SET_IN PUT_VERSION	<p><b>[Packet Type]</b>                  430</p> <p><b>[Command]</b>                  PAIR_RTCM_SET_INPUT_VERSION</p> <p><b>[Description]</b>                  Set RTCM input version.</p> <p><b>[Data Field]</b>                  \$PAIR430,&lt;Version&gt;*CS&lt;CR&gt;&lt;LF&gt;                  Version: Input version                  0: RTCM v2.x                  1: RTCM v3.x</p> <p><b>[Return]</b>                  1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR430,0*21\r\n ==&gt; set RTCM v2.x input</p> <p>Response:                      \$PAIR001,430,0*3C\r\n ==&gt; Success</p> </div>
PAIR_RTCM_GET_I NPUT_VERSION	<p><b>[Packet Type]</b>                  431</p> <p><b>[Command]</b>                  PAIR_RTCM_GET_INPUT_VERSION</p> <p><b>[Description]</b>                  Get RTCM input version.</p> <p><b>[Data Field]</b>                  \$PAIR431*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b>                  1. <b>PAIR_ACK</b> for send result.</p>

	<p>2. \$PAIR431,&lt;Version&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Version: Input version</p> <p>0: RTCM v2.x</p> <p>1: RTCM v3.x</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR431*3C\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,431,0*3D\r\n ==&gt; Success</p> <p style="padding-left: 20px;">\$PAIR431,0*20\r\n ==&gt; RTCM v2.x input</p> </div>
PAIR_RTCM_SET_OUTPUT_MODE	<p><b>[Packet Type]</b></p> <p>432</p> <p><b>[Command]</b></p> <p>PAIR_RTCM_SET_OUTPUT_MODE</p> <p><b>[Description]</b></p> <p>Set RTCM output mode.</p> <p><b>[Data Field]</b></p> <p>\$PAIR432,&lt;MODE&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>MODE: Measurement output mode (MSM4/MSM7)</p> <p>-1: Output None (Default)</p> <p>0: Output RTCM3.x with message type MSM4</p> <p>1: Output RTCM3.x with message type MSM7</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR432,1*22\r\n ==&gt; set RTCM3.x output with type MSM7</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,432,0*3E\r\n ==&gt; Success</p> </div>
PAIR_RTCM_GET_OUTPUT_MODE	<p><b>[Packet Type]</b></p> <p>433</p> <p><b>[Command]</b></p> <p>PAIR_RTCM_GET_OUTPUT_MODE</p> <p><b>[Description]</b></p> <p>Get RTCM output mode.</p> <p><b>[Data Field]</b></p>

	<p><b>\$PAIR433*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR433,&lt;MODE&gt;*CS&lt;CR&gt;&lt;LF&gt;</b> MODE: Measurement output mode (MSM4/MSM7) -1: Output None (Default) 0: Output RTCM3.x with message type MSM4 1: Output RTCM3.x with message type MSM7</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR433*3E\r\n</p> <p>Response: \$PAIR001,433,0*3F\r\n ==&gt; Success \$PAIR433,0*22\r\n ==&gt; RTCM3.x output with type MSM4</p> </div>
<p>PAIR_RTCM_SET_OUTPUT_ANT_PNT</p>	<p><b>[Packet Type]</b> 434</p> <p><b>[Command]</b> PAIR_RTCM_SET_OUTPUT_ANT_PNT</p> <p><b>[Description]</b> This command is to set enable/disable stationary antenna reference point for RTCM output.</p> <p><b>[Data Field]</b> <b>\$PAIR434,&lt;ENABLE&gt;*CS&lt;CR&gt;&lt;LF&gt;</b> ENABLE: Stationary antenna reference point (Message type 1005) 0: Disable 1: Enable</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR434,1*24\r\n ==&gt; set RTCM3.x output with message type 1005</p> <p>Response: \$PAIR001,434,0*38\r\n ==&gt; Success</p> </div>
<p>PAIR_RTCM_GET_OUTPUT_ANT_PNT</p>	<p><b>[Packet Type]</b> 435</p> <p><b>[Command]</b> PAIR_RTCM_GET_OUTPUT_ANT_PNT</p>

	<p><b>[Description]</b> Query setting of stationary antenna reference point for RTCM output.</p> <p><b>[Data Field]</b> \$PAIR435*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. PAIR_ACK for send result.</li> <li>2. \$PAIR435,&lt;ENABLE&gt;*CS&lt;CR&gt;&lt;LF&gt; ENABLE: Stationary antenna reference point (Message type 1005) 0: Disable 1: Enable</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR435*38\r\n</p> <p>Response: \$PAIR001,435,0*39\r\n ==&gt; Success \$PAIR435,1*25\r\n ==&gt; RTCM3.x output with message type 1005</p> </div>
PAIR_RTCM_SET_OUTPUT_EPHEMERIS	<p><b>[Packet Type]</b> 436</p> <p><b>[Command]</b> PAIR_RTCM_SET_OUTPUT_EPHEMERIS</p> <p><b>[Description]</b> This command is to set enable/disable RTCM output with satellite ephemeris.</p> <p><b>[Data Field]</b> \$PAIR436,&lt;ENABLE&gt;*CS&lt;CR&gt;&lt;LF&gt; ENABLE: 0: Disable 1: Enable</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. PAIR_ACK for send result.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR436,1*26\r\n ==&gt; set RTCM3.x output with satellite ephemeris</p> <p>Response: \$PAIR001,436,0*3A\r\n ==&gt; Success</p> </div>
PAIR_RTCM_GET_OUTPUT_EPHEMERIS	<p><b>[Packet Type]</b> 437</p>

	<p><b>[Command]</b>                  PAIR_RTCM_GET_OUTPUT_EPHEMERIS</p> <p><b>[Description]</b>                  Query setting of RTCM satellite ephemeris output.</p> <p><b>[Data Field]</b>                  \$PAIR437*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b>                  1. PAIR_ACK for send result.                  2. \$PAIR437,&lt;ENABLE&gt;*CS&lt;CR&gt;&lt;LF&gt;                  ENABLE:                  0: Disable                  1: Enable</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                      \$PAIR437*3A\r\n</p> <p>Response:                      \$PAIR001,437,0*3B\r\n ==&gt; Success                      \$PAIR437,1*27\r\n ==&gt; RTCM3.x output with satellite ephemeris</p> </div>
PAIR_RTCM_SET_STATION_ID	<p><b>[Packet Type]</b>                  442</p> <p><b>[Command]</b>                  PAIR_RTCM_SET_STATION_ID</p> <p><b>[Description]</b>                  This command is to set RTCM output station id.</p> <p><b>[Data Field]</b>                  \$PAIR442,&lt;StationID&gt;*CS&lt;CR&gt;&lt;LF&gt;                  StationID: range [0000 - 4095]</p> <p><b>[Return]</b>                  1. <u>PAIR_ACK</u> for send result.</p> <p><b>[Example]</b></p> <p>Send:                  \$PAIR442,3335*12\r\n ==&gt; set RTCM3.x output with station id as 3335</p> <p>Response:                  \$PAIR001,442,0*39\r\n ==&gt; Success</p>
PAIR_RTCM_GET_STATION_ID	<p><b>[Packet Type]</b>                  443</p>

	<p><b>[Command]</b> PAIR_RTCM_GET_STATION_ID</p> <p><b>[Description]</b> Query setting of RTCM station id.</p> <p><b>[Data Field]</b> \$PAIR443*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <a href="#">PAIR ACK</a> for send result. 2. \$PAIR443,&lt;StationID&gt;*CS&lt;CR&gt;&lt;LF&gt; StationID: range [0000 - 4095]</p> <p><b>[Example]</b> Send: \$PAIR443*39\r\n Response: \$PAIR001,443,0*38\r\n ==&gt; Success \$PAIR443,3335*13\r\n ==&gt; RTCM3.x output 3335 as station id</p>
PAIR_EPOC_ENABLE	<p><b>[Packet Type]</b> 496</p> <p><b>[Command]</b> PAIR_EPOC_ENABLE</p> <p><b>[Description]</b> Enable or Disable EPOC</p> <p><b>[Data Field]</b> \$PAIR496,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt; Enable: Enable or disable 0: Disable 1: Enable</p> <p><b>[Return]</b> 1. <a href="#">PAIR ACK</a> for send result.</p> <p><b>[Example]</b> Send: \$PAIR496,1*2C\r\n <b>Response:</b> \$PAIR001,496,0*30\r\n ==&gt; Success</p>
PAIR_EPOC_SET_CONFIG	<p><b>[Packet Type]</b> 498</p> <p><b>[Command]</b></p>

	<p>PAIR_EPOCH_SET_CONFIG</p> <p><b>[Description]</b> Set EPOCH Configuration</p> <p><b>[Data Field]</b> \$PAIR498,&lt;Constellation&gt;*CS&lt;CR&gt;&lt;LF&gt; Constellation: EPOCH constellation setting, bit 0: GPS, bit 1: GAL, bit 2: BDS, bit 3: GLO, bit 4: QZS, expressed as a decimal value. Only G, G+E, G+C are available</p> <p><b>[Return]</b> 1. <a href="#">PAIR ACK</a> for send result.</p> <p><b>[Example]</b> Send: \$PAIR498,1*22\r\n Response: \$PAIR001,498,0*3E\r\n</p>
PAIR_EPOCH_CLEAR_DATA	<p><b>[Packet Type]</b> 507</p> <p><b>[Command]</b> PAIR_EPOCH_CLEAR_DATA</p> <p><b>[Description]</b> Clear All EPOCH data in NVRAM</p> <p><b>[Data Field]</b> \$PAIR507*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <a href="#">PAIR ACK</a> for send result.</p> <p><b>[Example]</b> Send: \$PAIR507*38\r\n Response \$PAIR001,507,0*39\r\n</p>
PAIR_EPOCH_GET_STATUS	<p><b>[Packet Type]</b> 508</p> <p><b>[Command]</b> PAIR_EPOCH_GET_STATUS</p> <p><b>[Description]</b> Get EPOCH status</p> <p><b>[Data Field]</b> \$PAIR508*CS&lt;CR&gt;&lt;LF&gt;</p>

	<p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR ACK</b> for send result.</li> <li>2. <b>\$PAIR508,&lt;Enabled&gt;,&lt;Constellation&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>            Enabled: 1: EPOC Enabled, 0: EPOC Disabled            Constellation: EPOC constellation in hexadecimal, bit 0: GPS, bit 1: GAL, bit 2: BDS, bit 3: GLO, bit 4: QZS</li> </ol> <p><b>[Example]</b></p> <p>Send: \$PAIR508*37\r\n</p> <p>Response: \$PAIR001,508,0*36\r\n \$PAIR508,0,1*36\r\n</p>
<p>PAIR_EPOC_GET_PREDICTION_STATUS</p>	<p><b>[Packet Type]</b> 509</p> <p><b>[Command]</b> PAIR_EPOC_GET_PREDICTION_STATUS</p> <p><b>[Note]</b> This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by PAIR_GNSS_SUBSYS_GET_STATUS.</p> <p><b>[Description]</b> Get EPOC prediction status</p> <p><b>[Data Field]</b> \$PAIR509,&lt;Constellation&gt;*CS&lt;CR&gt;&lt;LF&gt; Constellation: The constellation required bit 0: GPS, bit 1: GAL, bit 2: BDS, bit 3: GLO, bit 4: QZS, expressed in HEX</p> <p><b>[Data Field]</b></p> <ol style="list-style-type: none"> <li>1. PAIR_ACK for send result.</li> <li>2. <b>\$PAIR509,&lt;Prediction Status&gt;,&lt;Constellation&gt;,&lt;Satellite Status&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>            Prediction Status: The overall status of EPOC prediction. 1: Running, 2: Idle, 3: Init            Running: Prediction is in progress            Idle: All received ephemerides have been predicted            Init: EPOC does not receive any valid ephemeris            Constellation: Constellation shown in the next field            bit 0: GPS, bit 1: GAL, bit 2: BDS, bit 3: GLO, bit 4: QZS, expressed in HEX            Satellite Status: The satellites that have 3-day prediction data.            Bitwise. For example: 000000000000D51, sv 1,5,7,9,11,12 have finished 3-day prediction</li> </ol> <p><b>[Example]</b></p> <p>Send: \$PAIR509,1*2B\r\n</p>



	<p>Response:</p> <p>\$PAIR001,509,0*37\r\n</p> <p>\$PAIR509,1,1,000000000000D51*6A\r\n</p> <p><b>[Note]</b></p> <p>The command can only receive one constellation at a time.</p>
PAIR_NVRAM_AUTO_SAVING_ENABLE	<p><b>[Packet Type]</b></p> <p>510</p> <p><b>[Command]</b></p> <p>PAIR_NVRAM_AUTO_SAVING_ENABLE</p> <p><b>[Description]</b></p> <p>Enable/Disable navigation data auto saving from RTC RAM to flash.                  System will automatically save the data at the first fix and then every 30 minutes.</p> <p><b>[Data Field]</b></p> <p>\$PAIR510,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable:</p> <p>0: Disable</p> <p>1: Enable</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR ACK</a> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <p>\$PAIR510,1*23\r\n</p> <p>Response:</p> <p>\$PAIR001,510,0*3F\r\n</p> <p><b>[Note]</b></p> <p>This command can only be set in 1Hz.</p>
PAIR_NVRAM_SAVE_NAVIGATION_DATA	<p><b>[Packet Type]</b></p> <p>511</p> <p><b>[Command]</b></p> <p>PAIR_NVRAM_SAVE_NAVIGATION_DATA</p> <p><b>[Description]</b></p> <p>Save current navigation data from RTC RAM to flash.</p> <p><b>[Data Field]</b></p> <p>\$PAIR511*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR ACK</a> for send result.</p> <p><b>[Example]</b></p>

	<p>Send: \$PAIR511*3F\r\n</p> <p>Response: \$PAIR001,511,1*3F\r\n ==&gt; Processing \$PAIR001,511,0*3E\r\n ==&gt; Success</p> <p><b>[Note]</b> In multi-Hz, this command can only be set when the GNSS system is powered off, while 1Hz does not have this limitation.</p>
<p>PAIR_NVRAM_CLEAR_NAVIGATION_DATA</p>	<p><b>[Packet Type]</b> 512</p> <p><b>[Command]</b> PAIR_NVRAM_CLEAR_NAVIGATION_DATA</p> <p><b>[Description]</b> Clear navigation data in both RTC RAM and flash. Note: This command is only used for testing.</p> <p><b>[Data Field]</b> \$PAIR512*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b> Send: \$PAIR512*3C\r\n Response: \$PAIR001,512,0*3D\r\n</p>
<p>PAIR_NVRAM_SAVE_SETTING</p>	<p><b>[Packet Type]</b> 513</p> <p><b>[Command]</b> PAIR_NVRAM_SAVE_SETTING</p> <p><b>[Description]</b> Save the current configuration from RTC RAM to flash.</p> <p><b>[Data Field]</b> \$PAIR513*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b> Send: \$PAIR513*3D\r\n</p>

	<p>Response: \$PAIR001,513,0*3C\r\n</p> <p><b>[Note]</b>                  You need to send this command every time after modifying any parameters, if the HW not keep RTC power.                  Otherwise, the changes will be lost after system reboot and the GNSS module must be reconfigured again.                  If HW will keep RTC power, no need to use this command. The change of configuration will keep in the RTC RAM.                  In multi-Hz, this command can only be set when the GNSS system is powered off, while 1Hz does not have this limitation.</p>
PAIR_NVRAM_RESTORE_DEFAULT_SETTING	<p><b>[Packet Type]</b> 514</p> <p><b>[Command]</b> PAIR_NVRAM_RESTORE_DEFAULT_SETTING</p> <p><b>[Description]</b>                  Clear the current configuration and restore the default settings.                  This function does not support run time restore when GNSS is power on.                  Please send <b>PAIR_GNSS_SUBSYS_POWER_OFF</b> to power off GNSS before use this command.</p> <p><b>[Data Field]</b> \$PAIR514*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send: \$PAIR514*3A\r\n</p> <p>Response: \$PAIR001,514,0*3B\r\n</p>
PAIR_TIME_GET_CURRENT_TOW	<p><b>[Packet Type]</b> 596</p> <p><b>[Command]</b> PAIR_TIME_GET_CURRENT_TOW</p> <p><b>[Description]</b> Get current time of week in milliseconds.</p> <p><b>[Data Field]</b> \$PAIR596*CS&lt;CR&gt;&lt;LF&gt;</p>

	<p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR596,&lt;Validity&gt;,&lt;TOW&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>                      Validity: Validity of TOW.                          0: Invalid TOW.                          1: Valid TOW.                      TOW: Current time of week in milliseconds.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                          \$PAIR596*30\r\n</p> <p>Response:                          \$PAIR001,596,0*31\r\n ==&gt; Success                          \$PAIR596,1,96939680*03\r\n ==&gt; Valid current TOW</p> </div>
PAIR_TIME_GET_GNSS_TOW	<p><b>[Packet Type]</b> 597</p> <p><b>[Command]</b> PAIR_TIME_GET_GNSS_TOW</p> <p><b>[Description]</b> Get the last GNSS epoch's time of week in milliseconds.</p> <p><b>[Data Field]</b> <b>\$PAIR597*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR597,&lt;Validity&gt;,&lt;TOW&gt;*CS&lt;CR&gt;&lt;LF&gt;</b>                      Validity: Validity of TOW.                          0: Invalid TOW.                          1: Valid TOW.                      TOW: The last GNSS epoch's time of week in milliseconds.</li> </ol> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:                          \$PAIR597*31\r\n</p> <p>Response:                          \$PAIR001,597,0*30\r\n ==&gt; Success                          \$PAIR597,1,96710000*09\r\n ==&gt; Valid TOW of the last GNSS epoch</p> </div>
PAIR_LOW_POWER_ENTRY_RTC_MODE	<p><b>[Packet Type]</b> 650</p>

	<p><b>[Command]</b></p> <p>PAIR_LOW_POWER_ENTRY_RTC_MODE</p> <p><b>[Description]</b></p> <p>Shutdown all systems, including GNSS and other CM4 modules.</p> <p>CM4 will go into RTC-Mode after sending this command and cannot receive any commands. CM4 can be awoken by the timer or the RTC_EINT pin. All system resource will re-initialize after wake up.</p> <p><b>[Data Field]</b></p> <p>\$PAIR650,&lt;Second&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Second: the timer to leave RTC-Mode [Valid range: 0 and 10 ~ 62208000 (2 years)]</p> <p>'0' enter RTC-Mode without any timer</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR650,1*24\r\n</p> <p>Response:</p> <p>\$PAIR001,650,4*3C\r\n ==&gt; Parameter error</p> <p>Send:</p> <p>\$PAIR650,10*14\r\n</p> <p>Response:</p> <p>Enter RTC-Mode without any response and wake up after 10 seconds</p> </div> <p><b>[Note]</b></p> <p>S/SD EVK must require timer to enter RTC-Mode.</p>
PAIR_GLP_ENABLE	<p><b>[Packet Type]</b></p> <p>680</p> <p><b>[Command]</b></p> <p>PAIR_GLP_ENABLE</p> <p><b>[Note]</b></p> <p>This configuration will not keep in the flash or RTC RAM. Please send this command every time after the GNSS subsystem or main power reboots.</p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b></p> <p>This command is to activate low-power GLP mode.</p> <p>GLP mode supports 1-Hz PVT, GPS L1 only, and Fitness mode.</p> <p><b>[Data Field]</b></p> <p>\$PAIR680,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p>

	<p>Enable:</p> <p>0: Disable GLP</p> <p>1: Enable GLP</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR680,1*29\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,680,0*35\r\n ==&gt; Success</p> </div>
PAIR_GLP_GET_STA TUS	<p><b>[Packet Type]</b></p> <p>681</p> <p><b>[Command]</b></p> <p>PAIR_GLP_GET_STATUS</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b></p> <p>This command is to get low-power GLP mode setting</p> <p><b>[Data Field]</b></p> <p>\$PAIR681*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. \$PAIR681,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable:</p> <p>0: Disable GLP</p> <p>1: Enable GLP</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR681*35\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,681,0*34\r\n ==&gt; Success</p> <p style="padding-left: 20px;">\$PAIR681,1*28\r\n</p> </div>
PAIR_PERIODIC_SE T_MODE	<p><b>[Packet Type]</b></p> <p>690</p> <p><b>[Command]</b></p> <p>PAIR_PERIODIC_SET_MODE</p>

**[Note]**

This configuration will not keep in the flash or RTC RAM. Please send this command every time after the GNSS subsystem or main power reboots.

This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by **PAIR\_GNSS\_SUBSYS\_GET\_STATUS**.

**[Description]**

This command is used to set Periodic Power Saving Mode Settings.

There are two stages in periodic power saving mode (Run stage and Sleep stage), and it will change periodically according to the setting.

Run stage: the GNSS module measures and calculates the position.

Sleep stage: the GNSS module may enter power saving modes.

<Note> Sleep will be interrupted by any DSP corresponding PAIR command.

Any restart will force it to go back to normal mode.

For more detailed information, please refer to the Power Saving Mode chapter of Periodic Mode section in the

Airoha\_IoT\_SDK\_for\_GNSS\_Developers\_Guide under the doc folder in IoT\_SDK\_for\_Location package.

**[Data Field]**

**\$PAIR690,<Mode>,<FirstRun>,<FirstSleep>,<SecondRun>,<SecondSleep>\*CS<CR><LF>**

Mode:

0: Disable periodic mode.

1: Smart periodic mode. In this mode, GNSS system dynamically increases run time in order to collect more navigation data.

2: Strict periodic mode. In this mode, GNSS system periodically forces entry into low-power mode.

If <Mode> is 1 or 2, it needs the following parameter for low-power periodic mode.

FirstRun: Interval in seconds to exit the minimum power sleep mode and get a new position fix. [Range: 3~518400 s]

FirstSleep: Duration in seconds to get a fix (or attempt to get a fix) before switching from running mode back to a minimum power sleep mode. [Range: 3~518400 s]

SecondRun: GNSS system will use "second run time" instead of "run time" setting when there is no signal. [Range: 0 or 3~518400 s]

The second run time duration can be "0" only when the second sleep time is "0".

SecondSleep: GNSS system will use "second sleep time" instead of "sleep time" setting when there is no signal. [Range: 0 or 3~518400 s]

The second sleep time duration can be "0" only when the second run time is "0".

**[Return]**

1. **PAIR\_ACK** for send result.

**[Example]**

	<p>Send: \$PAIR690,1,21,39,48,72*28\r\n</p> <p>Response: \$PAIR001,690,0*34\r\n ==&gt; Success</p> <p>Send: \$PAIR690,0*29\r\n ==&gt; Normal mode</p> <p>Response: \$PAIR001,690,0*34\r\n ==&gt; Success</p>
PAIR_PERIODIC_GET_MODE	<p><b>[Packet Type]</b> 691</p> <p><b>[Command]</b> PAIR_PERIODIC_GET_MODE</p> <p><b>[Note]</b> This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b> This command is used to get Periodic Power Saving Mode Settings. For more detailed information, please refer to the Power Saving Mode chapter of Periodic Mode section in the Airoha_IoT_SDK_for_GNSS_Developers_Guide under the doc folder in IoT_SDK_for_Location package.</p> <p><b>[Data Field]</b> \$PAIR691*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <a href="#">PAIR_ACK</a> for send result.</li> <li>2. \$PAIR691,&lt;Mode&gt;,&lt;FirstRun&gt;,&lt;FirstSleep&gt;,&lt;SecondRun&gt;,&lt;SecondSleep&gt;*CS&lt;CR&gt;&lt;LF&gt;</li> </ol> <p>Mode:</p> <p>0: Disable periodic mode.</p> <p>1: Smart periodic mode. In this mode, GNSS system dynamically increases run time in order to collect more navigation data.</p> <p>2: Strict periodic mode. In this mode, GNSS system periodically forces entry into low-power mode.</p> <p>FirstRun: Interval in seconds to exit the minimum power sleep mode and get a new position fix. [Range: 3~518400 s]</p> <p>FirstSleep: Duration in seconds to get a fix (or attempt to get a fix) before switching from running mode back to a minimum power sleep mode. [Range: 3~518400 s]</p>



	<p>SecondRun: GNSS system will use "second run time" instead of "run time" setting when there is no signal. [Range: 0 or 3~518400 s]</p> <p>SecondSleep: GNSS system will use "second sleep time" instead of "sleep time" setting when there is no signal. [Range: 0 or 3~518400 s]</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR691*34\r\n</p> <p>Response: \$PAIR001,691,1*34\r\n \$PAIR691,1,21,39,48,72*29\r\n</p> <p>Send: \$PAIR691*34\r\n</p> <p>Response: \$PAIR001,691,1*34\r\n \$PAIR691,0,21,39,48,72*28\r\n ==&gt; Normal mode</p> </div>
<p>PAIR_DTM_ENABLE</p>	<p><b>[Packet Type]</b> 720</p> <p><b>[Command]</b> PAIR_DTM_ENABLE</p> <p><b>[Note]</b> This configuration will not keep in the flash or RTC RAM. Please send this command every time after the GNSS subsystem or main power reboots. This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <b>PAIR_GNSS_SUBSYS_GET_STATUS</b>.</p> <p><b>[Description]</b> The GNSS Duty tracking mode is a duty cycle concept to ensure good performance and low power consumption in different environments. This command is to activate Duty tracking mode. For more detailed information, please refer to the Power Saving Mode chapter of Duty tracking mode section in the Airoha_IoT_SDK_for_GNSS_Developers_Guide under the doc folder in IoT_SDK_for_Location package.</p> <p><b>[Data Field]</b> \$PAIR720,&lt;Enable&gt;,&lt;Update Period&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable: 0: Disable Duty tracking mode 1: Enable Duty tracking mode</p>

	<p>Update Period: Position update period Range: 2,5,10,20,30,60 (s)</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Enable:</p> <p>Send: \$PAIR720,1,2*3C\r\n</p> <p>Response: \$PAIR001,720,0*3E\r\n ==&gt; Success</p> <p>Disable:</p> <p>Send: \$PAIR720,0*23\r\n</p> <p>Response: \$PAIR001,720,0*3E\r\n ==&gt; Success</p> </div>
<p>PAIR_DTM_GET_ST ATUS</p>	<p><b>[Packet Type]</b></p> <p>721</p> <p><b>[Command]</b></p> <p>PAIR_DTM_GET_STATUS</p> <p><b>[Description]</b></p> <p>This command is to get Duty tracking mode configuration setting.</p> <p><b>[Data Field]</b></p> <p>\$PAIR721*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. \$PAIR721,&lt;Enable&gt;,&lt;Update Period&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable:</p> <p>0: Duty tracking mode is disabled. 1: Duty tracking mode is enabled.</p> <p>Update Period: Position update period Range: 2,5,10,20,30,60 (s)</p> <p>If Duty tracking mode is disabled, the value will be 1.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR721*3E\r\n</p> <p>Response: \$PAIR001,721,0*3F\r\n ==&gt; Success</p> </div>

	\$PAIR721,1,2*3D\r\n
PAIR_FLP_ENABLE	<p><b>[Packet Type]</b> 730</p> <p><b>[Command]</b> PAIR_FLP_ENABLE</p> <p><b>[Note]</b> This configuration will not keep in the flash or RTC RAM. Please send this command every time after the GNSS subsystem or main power reboots. This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b> The fitness low power mode is a concept to ensure good performance and low power consumption in different environments. This command is to activate fitness low power mode. For more detailed information, please refer to the Power Saving Mode chapter of fitness low power mode section in the Airoha_IoT_SDK_for_GNSS_Developers_Guide under the doc folder in IoT_SDK_for_Location package. This command is only supported under FITNESS navigation mode.</p> <p><b>[Data Field]</b> \$PAIR730,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt; Enable: 0: Disable fitness low-power mode 1: Enable fitness low-power mode</p> <p><b>[Return]</b> 1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b></p> <p>Enable: Send: \$PAIR730,1*23\r\n Response: \$PAIR001,730,0*3F\r\n ==&gt; Success</p> <p>Disable: Send: \$PAIR730,0*22\r\n Response: \$PAIR001,730,0*3F\r\n ==&gt; Success</p>

PAIR_FLP_GET_STATUS	<p><b>[Packet Type]</b> 731</p> <p><b>[Command]</b> PAIR_FLP_GET_STATUS</p> <p><b>[Description]</b> This command is to get fitness low-power mode configuration setting. This command is only supported under FITNESS navigation mode.</p> <p><b>[Data Field]</b> \$PAIR731*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. PAIR_ACK for send result. 2. \$PAIR731,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt; Enable: 0: Fitness low-power mode is disabled. 1: Fitness low-power mode is enabled.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;">                 Send:                  \$PAIR731*3F\r\n                  Response:                  \$PAIR001,731,0*3E\r\n ==&gt; Success                  \$PAIR731,1*22\r\n             </div>
PAIR_ALP_ENABLE	<p><b>[Packet Type]</b> 732</p> <p><b>[Command]</b> PAIR_ALP_ENABLE</p> <p><b>[Note]</b> This configuration will not keep in the flash or RTC RAM. Please send this command every time after the GNSS subsystem or main power reboots. This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by PAIR_GNSS_SUBSYS_GET_STATUS.</p> <p><b>[Description]</b> The adaptive low power mode is a concept to ensure good performance and low power consumption in different environments. This command is to activate adaptive low power mode. For more detailed information, please refer to the Power Saving Mode chapter of adaptive low power mode section</p>

	<p>in the Airoha_IoT_SDK_for_GNSS_Developers_Guide under the doc folder in IoT_SDK_for_Location package.</p> <p>This command is only supported under NORMAL and FITNESS navigation modes.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR732,&lt;Mode&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Mode:</p> <p>0: Disable both adaptive low-power power saving mode and adaptive low-power performance mode</p> <p>1: Enable adaptive low-power power saving mode which might sacrifice GNSS performance in favor of a reduced power consumption.</p> <p>2: Enable adaptive low-power performance mode which achieves relatively good performance while keeping the power consumption low;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Enable:</p> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR732,1*21\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,732,0*3D\r\n ==&gt; Success</p> <p>Disable:</p> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR732,0*20\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,732,0*3D\r\n ==&gt; Success</p> </div>
<p>PAIR_ALP_GET_STATUS</p>	<p><b>[Packet Type]</b></p> <p>733</p> <p><b>[Command]</b></p> <p>PAIR_ALP_GET_STATUS</p> <p><b>[Description]</b></p> <p>This command is to get adaptive low-power mode configuration setting.</p> <p>This command is only supported under NORMAL and FITNESS navigation modes.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR733*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR733,&lt;Mode&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p>

	<p>Mode:</p> <p>0: Disable both adaptive low-power power saving mode and adaptive low-power performance mode</p> <p>1: adaptive low-power power saving mode is enabled.</p> <p>2: adaptive low-power performance mode is enabled.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR733*3D\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,733,0*3C\r\n ==&gt; Success</p> <p style="padding-left: 20px;">\$PAIR733,1*20\r\n</p> </div>
PAIR_PPS_SET_CONFIG_CMD	<p><b>[Packet Type]</b></p> <p>752</p> <p><b>[Command]</b></p> <p>PAIR_PPS_SET_CONFIG_CMD</p> <p><b>[Description]</b></p> <p>Configure the PPS settings.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR752,&lt;PPSType&gt;,&lt;PPSPulseWidth&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>PPSType: Availability</p> <p>"0", Disable</p> <p>"1", After the first fix</p> <p>"2", 3D fix only</p> <p>"3", 2D/3D fix only</p> <p>"4", Always</p> <p>PPSPulseWidth. PPS Pulse Width (unit in ms). [Range: 1 ~ 999]</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR752,2,100*39\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,752,0*3B\r\n ==&gt; Success</p> </div>
PAIR_PPS_SET_TIMING_PRODUCT	<p><b>[Packet Type]</b></p> <p>753</p> <p><b>[Command]</b></p>

	<p>PAIR_PPS_SET_TIMING_PRODUCT</p> <p><b>[Description]</b></p> <p>The timing product mode will enhance the PPS output timing accuracy.              mode1: For getting higher timing accuracy, SBAS/QZSS effects are disabled.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR753,&lt;Timing Product&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Timing Product:</p> <p>'0': Disable.</p> <p>'1': Enable timing product (remove SBAS/QZSS effects)</p> <p><b>[Return]</b></p> <p>1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b></p> <p>Send:</p> <pre>\$PAIR753,1*26\r\n</pre> <p>Response:</p> <pre>\$PAIR001,753,0*3A\r\n ==&gt; Success</pre> <p><b>[Note]</b></p> <p>Please measure the accuracy after the device collects all of the satellite almanac data.</p>
PAIR_PPS_SET_TIME TAG	<p><b>[Packet Type]</b></p> <p>755</p> <p><b>[Command]</b></p> <p>PAIR_PPS_SET_TIMETAG</p> <p><b>[Note]</b></p> <p>This command will get a failed response if GNSS-SubSys does not power on. You can get the GNSS-SubSys status by <a href="#">PAIR_GNSS_SUBSYS_GET_STATUS</a>.</p> <p><b>[Description]</b></p> <p>Set enable/disable output time tag and time base.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR755,&lt;Enable&gt;,&lt;Time_base&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Enable:</p> <p>"0", Disable.</p> <p>"1", Enable.</p> <p>Time_base: (Now only support GPS time base)</p> <p>"0", UTC.</p> <p>"1", GPS.</p> <p>"2", GLO.</p>

	<p>"3", GAL.                  "4", BDS.                  "5", NavIC.</p> <p><b>[Return]</b></p> <p>1. <u>PAIR_ACK</u> for send result.</p> <p><b>[Example]</b></p> <p>Send:                  \$PAIR755,1,1*3D\r\n</p> <p>Response:                  \$PAIR001,755,0*3C\r\n ==&gt; Success</p>
PAIR_PPS_GET_TIM ETAG_CONFIG	<p><b>[Packet Type]</b></p> <p>756</p> <p><b>[Command]</b></p> <p>PAIR_PPS_GET_TIMETAG_CONFIG</p> <p><b>[Description]</b></p> <p>Get time tag configuration including output status and time base.</p> <p><b>[Data Field]</b></p> <p>\$PAIR756*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>\$PAIR756,&lt;Enable&gt;,&lt;Time_base&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable:</p> <p>"0", Disable.                  "1", Enable.</p> <p>Time_base: (Now only support GPS time base)</p> <p>"0", UTC.                  "1", GPS.                  "2", GLO.                  "3", GAL.                  "4", BDS.                  "5", NavIC.</p> <p><b>[Example]</b></p> <p>Send:                  \$PAIR756*3E\r\n</p> <p>Response:                  \$PAIR001,756,0,1*22\r\n ==&gt; Success</p>
PAIR_PPS_SET_FALL	<p><b>[Packet Type]</b></p>



<p>ING_EDGE_TRIGGE R</p>	<p>757</p> <p><b>[Command]</b> PAIR_PPS_SET_FALLING_EDGE_TRIGGER</p> <p><b>[Description]</b> Set PPS trigger from rising edge to falling edge</p> <p><b>[Data Field]</b> \$PAIR757,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Timing Product: '0': Rising edge (Default). '1': Falling edge.</p> <p><b>[Return]</b> 1. <a href="#">PAIR_ACK</a> for send result.</p> <p><b>[Example]</b> Send: \$PAIR757,1*22\r\n Response: \$PAIR001,757,0*3E\r\n ==&gt; Success</p>
<p>PAIR_PPS_GET_FALLING_EDGE_TRIGGER</p>	<p><b>[Packet Type]</b> 758</p> <p><b>[Command]</b> PAIR_PPS_GET_FALLING_EDGE_TRIGGER</p> <p><b>[Description]</b> Get PPS trigger mode</p> <p><b>[Data Field]</b> \$PAIR758*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> \$PAIR758,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable: "0", Rising edge (Default). "1", Falling edge.</p> <p><b>[Example]</b> Send: \$PAIR758*30\r\n Response: \$PAIR001,758,0*31\r\n ==&gt; Success \$PAIR758,1*2D\r\n</p>

PAIR_PPS_GET_CON FIG	<p><b>[Packet Type]</b> 763</p> <p><b>[Command]</b> PAIR_PPS_GET_CONFIG</p> <p><b>[Description]</b> Get PPS config from PAIR750 / PAIR752.</p> <p><b>[Data Field]</b> \$PAIR63*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>\$PAIR763,&lt;PPS_by_user&gt;,&lt;Local_ms&gt;,&lt;Phase&gt;,&lt;PPSType&gt;,&lt;PPSPulseWidth&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>PPS_by_user:                      "1", PPS output by user.                      "0", PPS automatic output.</p> <p>Local_ms: Local receiver time tick. Range is from 0 to 4294967295 (2<sup>32</sup>-1). If PSS is enabled, this parameter aligns to TOW.</p> <p>Phase: For AG3335A, time tick phase range is from 0 to 1048575 (2<sup>20</sup>-1).                      For other models, time tick phase range is from 0 to 262143 (2<sup>18</sup>-1).                      If PPS is enabled, this parameter aligns to TOW.</p> <p>PPSType: Availability                      "0", Disable                      "1", After the first fix                      "2", 3D fix only                      "3", 2D/3D fix only                      "4", Always                      "9", 3D fix only after UTC sync to integer seconds</p> <p>PPSPulseWidth: PPS Pulse Width (unit in ms). [Range: 1 ~ 999]</p> <p><b>[Example]</b>                      Send:                      \$PAIR763*38\r\n</p> <p>Response:                      \$PAIR001,763,0*39\r\n ==&gt; Success                      \$PAIR763,0,0,0,2,100*27\r\n</p>
PAIR_RAW_ENABLE	<p><b>[Packet Type]</b> 830</p> <p><b>[Command]</b> PAIR_RAW_ENABLE</p> <p><b>[Description]</b></p>

	<p>Set enable/disable output binary raw measurement</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR830,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Enable:</p> <p>0: disable</p> <p>1: raw meas</p> <p>2: raw meas + sv info + pvt (including time offset data between GPS and GLO/GAL/BDS)</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR830,1*2C\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,830,0*30\r\n ==&gt; Success</p> </div>
PAIR_RAW_GET_ST ATUS	<p><b>[Packet Type]</b></p> <p>831</p> <p><b>[Command]</b></p> <p>PAIR_RAW_GET_STATUS</p> <p><b>[Description]</b></p> <p>Get enable/disable output binary raw measurement</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR831*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. <b>\$PAIR831,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Enable:</p> <p>0: disable</p> <p>1: raw meas</p> <p>2: raw meas + sv info + pvt</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR831*30\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,831,0*31\r\n ==&gt; Success</p> <p style="padding-left: 20px;">\$PAIR831,1*2D\r\n</p> </div>
PAIR_IO_SET_BAUD	<p><b>[Packet Type]</b></p>

<p>RATE</p>	<p>864</p> <p><b>[Command]</b> PAIR_IO_SET_BAUDRATE</p> <p><b>[Description]</b> Set port baud rate configuration.</p> <p><b>[Data Field]</b> \$PAIR864,&lt;Port_Type&gt;,&lt;Port_Index&gt;,&lt;Baudrate&gt;*CS&lt;CR&gt;&lt;LF&gt; Port_Type: HW Port Type. 0: UART Port_Index: HW Port Index UART - 0: UART0, 1: UART1, 2: UART2 Baudrate: the baud rate need config. Support 115200, 230400, 460800, 921600, 3000000</p> <p><b>[Return]</b> 1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR864,0,0,115200*1B\r\n</p> <p>Response: \$PAIR001,864,0*31\r\n ==&gt; Success</p> <p><b>[Note]</b> Must reboot the device after changing the port baud rate. The change will valid after reboot.</p> </div>
<p>PAIR_IO_GET_BAU DRATE</p>	<p><b>[Packet Type]</b> 865</p> <p><b>[Command]</b> PAIR_IO_GET_BAUDRATE</p> <p><b>[Description]</b> Get port baud rate configuration.</p> <p><b>[Data Field]</b> \$PAIR865,&lt;Port_Type&gt;,&lt;Port_Index&gt;*CS&lt;CR&gt;&lt;LF&gt; Port_Type: HW Port Type. 0: UART Port_Index: HW Port Index UART - 0: UART0, 1: UART1, 2: UART2</p> <p><b>[Return]</b> 1. PAIR_ACK for send result. 2. \$PAIR865,&lt;Baudrate&gt;*CS&lt;CR&gt;&lt;LF&gt;</p>

	<p>Baudrate: the baud rate need config. Support 115200, 230400, 460800, 921600, 3000000</p> <p><b>[Example]</b></p> <p>Send: \$PAIR865,0,0*31\r\n</p> <p>Response: \$PAIR001,865,0*30\r\n ==&gt; Success \$PAIR865,115200*1A\r\n ==&gt; Get UART0 baud rate is 115200.</p> <p><b>[Note]</b> Must reboot the device after changing the port baud rate.</p>
<p>PAIR_IO_SET_FLOW _CONTROL</p>	<p><b>[Packet Type]</b> 866</p> <p><b>[Command]</b> PAIR_IO_SET_FLOW_CONTROL</p> <p><b>[Description]</b> Set port flow control configuration.</p> <p><b>[Data Field]</b> \$PAIR866,&lt;Port_Type&gt;,&lt;Port_Index&gt;,&lt;Flow_control&gt;*CS&lt;CR&gt;&lt;LF&gt; Port_Type: HW Port Type. 0: UART Port_Index: HW Port Index UART - 0: UART0, 1: UART1, 2: UART2 Flow_control: 0, disable flow control. 1, enable SW flow control. 2, enable HW flow control.</p> <p><b>[Return]</b> 1. PAIR_ACK for send result.</p> <p><b>[Example]</b></p> <p>Send: \$PAIR866,0,2,1*2D\r\n ==&gt; Set UART2 SW Flow Control ON</p> <p>Response: \$PAIR001,866,0*33\r\n ==&gt; Success</p> <p><b>[Note]</b> Must reboot the device after changing the flow control type. The change will valid after reboot.</p>
<p>PAIR_IO_GET_FLO W_CONTROL</p>	<p><b>[Packet Type]</b> 867</p> <p><b>[Command]</b> PAIR_IO_GET_FLOW_CONTROL</p>

	<p><b>[Description]</b> Get port SW flow control configuration.</p> <p><b>[Data Field]</b> \$PAIR867,&lt;Port_Type&gt;,&lt;Port_Index&gt;*CS&lt;CR&gt;&lt;LF&gt; Port_Type: HW Port Type. 0: UART Port_Index: HW Port Index UART - 0: UART0, 1: UART1, 2: UART2</p> <p><b>[Return]</b> 1. PAIR_ACK for send result. 2. \$PAIR867,&lt;sw_flow_control&gt;*CS&lt;CR&gt;&lt;LF&gt; Flow_control: 0, disable flow control. 1, enable SW flow control. 2, enable HW flow control.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send: \$PAIR867,0,2*31\r\n</p> <p>Response: \$PAIR001,867,0*32\r\n \$PAIR867,0*2F\r\n ==&gt; Get UART2 Flow Control OFF</p> </div>
<p>PAIR_GEOFENCE_SET_CONFIG</p>	<p><b>[Packet Type]</b> 890</p> <p><b>[Command]</b> PAIR_GEOFENCE_SET_CONFIG</p> <p><b>[Description]</b> This command is used to set Geofencing configuration.</p> <p><b>[Data Field]</b> \$PAIR890,&lt;FenceNum&gt;,&lt;ConfLvl&gt;,&lt;Lat1&gt;,&lt;Lon1&gt;,&lt;Rad1&gt;,...,&lt;RadN&gt;*CS&lt;CR&gt;&lt;LF&gt; FenceNum(N): Number of geofences, the value is limited to 4. When the value is set to 0, the geofencing function is disabled. ConfLvl: The confidence level for state evaluation. '0' No requirement '1' 1-Sigma (68%) '2' 2-Sigma (95%) '3' 3-Sigma (99.7%) '4' 4-Sigma (99.9999%) '5' 5-Sigma (99.999999%) Lat: Latitude of the geofence circle center (deg) Lon: Longitude of the geofence circle center (deg)</p>

	<p>Rad: Radius of the geofence circle (m)</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Enable the geofencing function:</p> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR890,1,1,25.0567,121.5743,30*20\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,890,0*3A\r\n ==&gt; Success</p> <p>Disable the geofencing function:</p> <p>Send:</p> <p style="padding-left: 20px;">\$PAIR890,0*27\r\n</p> <p>Response:</p> <p style="padding-left: 20px;">\$PAIR001,890,0*3A\r\n ==&gt; Success</p> </div>
<p>PAIR_GEOFENCE_GET_CONFIG</p>	<p><b>[Packet Type]</b></p> <p>891</p> <p><b>[Command]</b></p> <p>PAIR_GEOFENCE_GET_CONFIG</p> <p><b>[Description]</b></p> <p>This command is used to get Geofencing configuration.</p> <p><b>[Data Field]</b></p> <p>\$PAIR891*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. \$PAIR891,&lt;FenceNum&gt;,&lt;ConfLvl&gt;,&lt;Lat1&gt;,&lt;Lon1&gt;,&lt;Rad1&gt;,&lt;Rad2&gt;,&lt;Rad3&gt;,&lt;Rad4&gt;,&lt;Rad5&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>FenceNum(N): Number of geofences, the value is limited to 4.</p> <p>ConfLvl: The confidence level for state evaluation.</p> <p style="padding-left: 20px;">'0' No requirement</p> <p style="padding-left: 20px;">'1' 1-Sigma (68%)</p> <p style="padding-left: 20px;">'2' 2-Sigma (95%)</p> <p style="padding-left: 20px;">'3' 3-Sigma (99.7%)</p> <p style="padding-left: 20px;">'4' 4-Sigma (99.9999%)</p> <p style="padding-left: 20px;">'5' 5-Sigma (99.999999%)</p> <p>Lat: Latitude of the geofence circle center (deg)</p> <p>Lon: Longitude of the geofence circle center (deg)</p> <p>Rad: Radius of the geofence circle (m)</p> <p><b>[Example]</b></p>

<p>PAIR_GEOFENCE_SET_GPIO_POLARITY</p>	<p>Send: \$PAIR891*3A\r\n</p> <p>Response: \$PAIR001,891,0*3B\r\n ==&gt; Success \$PAIR891,1,1,25.0567,121.5743,30*21\r\n</p> <p><b>[Packet Type]</b> 892</p> <p><b>[Command]</b> PAIR_GEOFENCE_SET_GPIO_POLARITY</p> <p><b>[Description]</b> This command is used to set GPIO polarity for geofencing combined state.</p> <p><b>[Data Field]</b> \$PAIR892,&lt;GPiOPolarity&gt;*CS&lt;CR&gt;&lt;LF&gt; GPiOPolarity: Pin polarity. '0' Low means outside '1' Low means inside Unknown state is always High.</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p>
<p>PAIR_LOCUS_ENABLE</p>	<p>Send: \$PAIR892,1*24\r\n</p> <p>Response: \$PAIR001,892,0*38\r\n ==&gt; Success</p> <p><b>[Packet Type]</b> 900</p> <p><b>[Command]</b> PAIR_LOCUS_ENABLE</p> <p><b>[Description]</b> Enable or disable LOCUS save data.</p> <p><b>[Data Field]</b> \$PAIR900,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt; Enable: Enable or disable '0': Disable '1': Enable</p> <p><b>[Return]</b></p>



<p>PAIR_LOCUS_GET_S TATUS</p>	<p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send: \$PAIR900,1*2E\r\n ==&gt; Enable LOCUS</p> <p>Response: \$PAIR001,900,0*32\r\n ==&gt; Enable Success</p> <hr/> <p><b>[Packet Type]</b> 901</p> <p><b>[Command]</b> PAIR_LOCUS_GET_STATUS</p> <p><b>[Description]</b> Get LOCUS status.</p> <p><b>[Data Field]</b> \$PAIR901*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. \$PAIR901,&lt;Enable&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Enable: Enable or disable</p> <p>'0': Disable</p> <p>'1': Enable</p> <p><b>[Example]</b></p> <p>Send: \$PAIR901*32\r\n</p> <p>Response: \$PAIR001,901,0*33\r\n</p> <p>\$PAIR901,0*2E\r\n ==&gt; LOCUS is disable</p>
<p>PAIR_LOCUS_SET_ MODE</p>	<p><b>[Packet Type]</b> 902</p> <p><b>[Command]</b> PAIR_LOCUS_SET_MODE</p> <p><b>[Description]</b> Set LOCUS saving mode.</p> <p><b>[Data Field]</b> \$PAIR902,&lt;Mode&gt;,&lt;Check_3D_Fix&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Mode: Saving Mode</p> <p>Normal, (1 &lt;&lt; 0). Record per fix.</p>

<p>PAIR_LOCUS_GET_MODE</p>	<p>Out of time, (1 &lt;&lt; 1). Record every N s. N is customer configuration (<b>PAIR_LOCUS_SET_THRESHOLD</b>).</p> <p>Out of speed, (1 &lt;&lt; 2). Record after speed more than N m/s. N is customer configuration (<b>PAIR_LOCUS_SET_THRESHOLD</b>).</p> <p>Out of distance, (1 &lt;&lt; 3). Record after distance more than N m. N is customer configuration (<b>PAIR_LOCUS_SET_THRESHOLD</b>).</p> <p>Before entry sleep, (1 &lt;&lt; 4). Record before entry sleep.</p> <p>User control, (1 &lt;&lt; 5). Record after user send <b>PAIR_LOCUS_LOG_NOW</b>.</p> <p>Check_3D_Fix: Need check 3D fix or not.</p> <p>0: not check.</p> <p>1: need check. If set this type as 1, system will not save the location without 3D fixed.</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p>
	<p>Send:</p> <p>\$PAIR902,6,1*36\r\n ==&gt; Set mode as out of time &amp; out of speed mode. Need check 3D fix.</p> <p>Response:</p> <p>\$PAIR001,902,0*30\r\n ==&gt; Set success.</p> <p><b>[Note]</b></p> <p>Must disable LOCUS saving before send this command.</p> <p><b>[Packet Type]</b></p> <p>903</p> <p><b>[Command]</b></p> <p>PAIR_LOCUS_GET_MODE</p> <p><b>[Description]</b></p> <p>Get LOCUS saving mode.</p> <p><b>[Data Field]</b></p> <p>\$PAIR903*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p>2. \$PAIR903,&lt;Mode&gt;,&lt;Check_3D_Fix&gt;*CS&lt;CR&gt;&lt;LF&gt;</p> <p>Mode: Saving Mode</p> <p>Normal, (1 &lt;&lt; 0). Record per fix.</p> <p>Out of time, (1 &lt;&lt; 1). Record every N s. N is customer configuration (<b>PAIR_LOCUS_SET_THRESHOLD</b>).</p> <p>Out of speed, (1 &lt;&lt; 2). Record after speed more than N m/s. N is customer configuration (<b>PAIR_LOCUS_SET_THRESHOLD</b>).</p> <p>Out of distance, (1 &lt;&lt; 3). Record after distance more than N m. N is customer configuration (<b>PAIR_LOCUS_SET_THRESHOLD</b>).</p>

<p>PAIR_LOCUS_SET_T HRESHOLD</p>	<p>Before entry sleep, (1 &lt;&lt; 4). Record before going to sleep.</p> <p>User control, (1 &lt;&lt; 5). Record after user send <b>PAIR_LOCUS_LOG_NOW</b>.</p> <p>Check_3D_Fix: Need check 3D fix or not.</p> <p>0: not check.</p> <p>1: need check. If set this type as 1, system will not save the location without 3D fixed.</p> <p><b>[Example]</b></p> <p>Send: \$PAIR903*30\r\n</p> <p>Response: \$PAIR001,903,0*31\r\n \$PAIR903,6,1*37\r\n ==&gt; LOCUS saving mode is out of time &amp; out of speed mode. Need check 3D fix.</p>
	<p><b>[Packet Type]</b> 904</p> <p><b>[Command]</b> PAIR_LOCUS_SET_THRESHOLD</p> <p><b>[Description]</b> Set LOCUS mode threshold.</p> <p><b>[Data Field]</b> <b>\$PAIR904,&lt;Mode&gt;,&lt;Threshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Mode: Saving Mode</p> <p>0: Out of time mode.</p> <p>1: Out of speed mode.</p> <p>2: Out of distance mode.</p> <p>Threshold: The threshold of saving mode.</p> <p>If mode == 0, out of time mode, the time threshold is 1s ~ 12hours. Unit is second. Default is 15s.</p> <p>If mode == 1, out of speed mode, the speed threshold is 1m/s ~ 100m/s. Unit is meters/second. Default is 1m/s.</p> <p>If mode == 2, out of distance mode, the distance threshold is 1m ~ 50000m. Unit is meter. Default is 1m.</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <p>Send: \$PAIR904,1,5*33\r\n ==&gt; Set out of time mode threshold is 5s.</p> <p>Response:</p>

PAIR_LOCUS_GET_THRESHOLD	<p>\$PAIR001,904,0*36\r\n ==&gt; Set success. LOCUS will save record every 5s.</p> <p><b>[Note]</b></p> <ol style="list-style-type: none"> <li>1. Must disable LOCUS saving before send this command.</li> <li>2. If the threshold out of range, it responds with a parameter error (" \$PAIR001,904,4*32\r\n").</li> </ol> <p><b>[Packet Type]</b></p> <p>905</p> <p><b>[Command]</b></p> <p>PAIR_LOCUS_GET_THRESHOLD</p> <p><b>[Description]</b></p> <p>Get LOCUS mode threshold.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR905,&lt;Mode&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Mode: Saving Mode</p> <ul style="list-style-type: none"> <li>0: Out of time mode.</li> <li>1: Out of speed mode.</li> <li>2: Out of distance mode.</li> </ul> <p><b>[Return]</b></p> <ol style="list-style-type: none"> <li>1. <b>PAIR_ACK</b> for send result.</li> <li>2. <b>\$PAIR905,&lt;Threshold&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></li> </ol> <p>Threshold: The threshold of saving mode.</p> <p>If mode == 0, out of time mode, the time threshold is 1s ~ 12hours. Unit is second. Default is 15s.</p> <p>If mode == 1, out of speed mode, the speed threshold is 1m/s ~ 100m/s. Unit is meters/second. Default is 1m/s.</p> <p>If mode == 2, out of distance mode, the distance threshold is 1m ~ 50000m. Unit is meter. Default is 1m.</p> <p><b>[Example]</b></p> <p>Send:</p> <p>\$PAIR905,0*2A\r\n ==&gt; Get time threshold</p> <p>Response:</p> <p>\$PAIR001,905,0*37\r\n</p> <p>\$PAIR905,15*1E\r\n ==&gt; Time threshold is 15s.</p>
PAIR_LOCUS_CLEAR	<p><b>[Packet Type]</b></p> <p>906</p> <p><b>[Command]</b></p> <p>PAIR_LOCUS_CLEAR</p> <p><b>[Description]</b></p>

	<p>Clear LOCUS Data.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR906,&lt;Type&gt;*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p>Type: Clear Type</p> <p>0: Clear record data and restore to default setting (configuration in gnss_config.bin).</p> <p>1: Clear record data only.</p> <p>2: Clear user setting. Restore to default setting.</p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR906,0*29\r\n</p> <p>Response:</p> <p>\$PAIR001,906,0*34\r\n</p> </div>
PAIR_LOCUS_LOG_NOW	<p><b>[Note]</b></p> <p>Must disable LOCUS saving before send this command.</p> <p><b>[Packet Type]</b></p> <p>907</p> <p><b>[Command]</b></p> <p>PAIR_LOCUS_LOG_NOW</p> <p><b>[Description]</b></p> <p>Save current location data.</p> <p><b>[Data Field]</b></p> <p><b>\$PAIR907*CS&lt;CR&gt;&lt;LF&gt;</b></p> <p><b>[Return]</b></p> <p>1. <b>PAIR_ACK</b> for send result.</p> <p><b>[Example]</b></p> <div style="border: 1px solid black; padding: 5px;"> <p>Send:</p> <p>\$PAIR907*34\r\n</p> <p>Response:</p> <p>\$PAIR001,907,0*35\r\n</p> </div>
PAIR_LOCUS_GET_DATA	<p><b>[Note]</b></p> <p>Must keep user control (1 &lt;&lt; 5) in saving mode if need use this command.</p> <p><b>[Packet Type]</b></p> <p>908</p> <p><b>[Command]</b></p> <p>PAIR_LOCUS_GET_DATA</p> <p><b>[Description]</b></p>

Get all record data.

**[Data Field]**

**\$PAIR908,<Type>\*CS<CR><LF>**

Type: Response type.

0: Response as NMEA.

1: Response as PAIR command.

**[Return]**

1. **PAIR\_ACK** for send result.

2. **\$PAIR908,0\*CS<CR><LF>**

LOCUS read begin

3. **\$PAIR908,1,<Record\_Num>,<Record\_Size>\*CS<CR><LF>**

LOCUS read information.

Record\_Num: the total record numbers.

Record\_Size: the size of data per record.

4. LOGGA + LORMC.

If type is 0, system will response LOGGA + GPGGA. The format is same as GPGGA + GPRMC.

5. **\$PAIR908,2,<UTC>,<Fix\_Type>,<Lat>,<Lon>,<Heighing>,<Speed>,<Heading>,<HDO P>,<SatNo>\*CS<CR><LF>**

If type is 1, system will response PAIR908,2,xxxx list for every record.

None saved data will show 0.

6. **\$PAIR908,3\*CS<CR><LF>**

LOCUS read end.

**[Example]**

Send:

```
$PAIR908,0*27\r\n
```

Response:

```
$PAIR001,908,0*3A\r\n
```

```
$PAIR908,0*27\r\n
```

```
$PAIR908,1,2,16*13\r\n
```

```
$LOGGA,080931.000,011772.4267,N,0016183.7702,E,1,0,0.0,0.53,M,,M,,*59\r\n
```

```
$LORMC,080931.000,A,011772.4267,N,0016183.7702,E,260320,,,A,V*C\r\n
```

```
$LOGGA,080932.000,011772.4267,N,0016183.7702,E,1,0,0.0,0.53,M,,M,,*5A\r\n
```

```
$LORMC,080932.000,A,011772.4267,N,0016183.7702,E,260320,,,A,V*F\r\n
```

```
$PAIR908,3*24\r\n
```

Send:

```
$PAIR908,1*26\r\n
```

Response:

```
$PAIR001,908,0*3A\r\n
```

<p>PAIR_LOCUS_GET_RECORD_NUM</p>	<pre>\$PAIR908,0*27\r\n \$PAIR908,2,5EA541BB,01,12341A1C,3E06BA8C,0210,0000,0000,0000,00*04\r\n \$PAIR908,2,5EA541BC,01,12341A1B,3E06BA8A,0210,0000,0000,0000,00*06\r\n \$PAIR908,1,2,16*13\r\n \$PAIR908,3*24\r\n</pre> <p><b>[Note]</b> Must disable LOCUS saving before send this command.</p> <p><b>[Packet Type]</b> 909</p> <p><b>[Command]</b> PAIR_LOCUS_GET_RECORD_NUM</p> <p><b>[Description]</b> Get total record number.</p> <p><b>[Data Field]</b> \$PAIR909*CS&lt;CR&gt;&lt;LF&gt;</p> <p><b>[Return]</b> 1. <b>PAIR_ACK</b> for send result. 2. \$PAIR909,&lt;Record_Num&gt;*CS&lt;CR&gt;&lt;LF&gt; Record_Num: total record number.</p> <p><b>[Example]</b></p> <pre>Send: \$PAIR909*3A\r\n Response: \$PAIR001,909,0*3B\r\n \$PAIR909,15*12\r\n ==&gt; LOCUS has save 15 records.</pre>

## Appendix - How to get checksum

Checksum value are the XOR checksum of the data between Preamble and '\*'.

Example: \$PMTK666,666\*2E\0d\0a ==> Checksum value "2E" are the XOR checksum of "PMTK666,666".

Without "\$" and without "\*".

Calculation formula:

- $\text{checksum} \wedge = \text{*buffer}$
- $\text{CHK1} = (\text{checksum} \gg 4) \& 0x0F$
- $\text{CHK2} = \text{checksum} \& 0x0F$

This is example code to get checksum value.

### Example

```
void get_full_pair_command(int8_t* buf, int32_t buf_len, int8_t* temp_buf, int32_t temp_buf_len)
{
    const int32_t wait_ticket = 0xFFFFFFFF;
    int32_t ret_len = 0;
    int8_t* ind;
    uint8_t checkSumL = 0, checkSumR;

    if (buf_len + 6 > temp_buf_len) {
```



```
        return;
    }

ind = buf;

while(ind - buf < buf_len) {
    checkSumL ^= *ind;
    ind++;
}

temp_buf[0] = '$';
memcpy(temp_buf + 1, buf, buf_len);
temp_buf[buf_len + 1] = '*';
checkSumR = checkSumL & 0x0F;
checkSumL = (checkSumL >> 4) & 0x0F;
temp_buf[buf_len + 2] = checkSumL >= 10 ? checkSumL + 'A' - 10 : checkSumL + '0';
temp_buf[buf_len + 3] = checkSumR >= 10 ? checkSumR + 'A' - 10 : checkSumR + '0';
temp_buf[buf_len + 4] = '\\';
temp_buf[buf_len + 5] = '0';
temp_buf[buf_len + 6] = 'd';
temp_buf[buf_len + 7] = '\\';
temp_buf[buf_len + 8] = '0';
temp_buf[buf_len + 9] = 'a';
temp_buf[buf_len + 10] = '\\0';
buf_len += 10;
}

void main()
{
    char command[1024] = {0};
    char command_checksum[1024] = {0};
    printf("Press command:\n");
    scanf("%s",command);
    get_full_pair_command(command, strlen(command), command_checksum, 1024);
    printf("%s\n",command_checksum);
    system("pause");
}
```

Input : PAIR666,666

Output : \$PAIR666,666\*26\0d\0a

## Appendix - Datum List

All the datum type supported are shown in this table.

No	Datum	Region
0	WGS1984	International
1	Tokyo	Japan
2	Tokyo	Mean For Japan, South Korea, Okinawa
3	User Setting	User Setting
4	Adindan	Burkina Faso
5	Adindan	Cameroon
6	Adindan	Ethiopia
7	Adindan	Mali
8	Adindan	Mean For Ethiopia, Sudan
9	Adindan	Senegal
10	Adindan	Sudan
11	Afgooye	Somalia
12	Ain El Abd1970	Bahrain
13	Ain El Abd1970	Saudi Arabia

14	American Samoa1962	American Samoa Islands
15	Anna 1 Astro1965	Cocos Island
16	Antigua Island Astro1943	Antigua(Leeward Islands)
17	Arc1950	Botswana
18	Arc1950	Burundi
19	Arc1950	Lesotho
20	Arc1950	Malawi
21	Arc1950	Mean For Botswana, Lesotho, Malawi, Swaziland, Zaire, Zambia, Zimbabwe
22	Arc1950	Swaziland
23	Arc1950	Zaire
24	Arc1950	Zambia
25	Arc1950	Zimbabwe
26	Arc1960	Mean For Kenya Tanzania
27	Arc1960	Kenya
28	Arc1960	Tanzania
29	Ascension Island1958	Ascension Island
30	Astro Beacon E 1945	Iwo Jima
31	Astro Dos 71/4	St Helena Island
32	Astro Tern Island (FRIG) 1961	Tern Island
33	Astronomical Station 1952	Marcus Island
34	Australian Geodetic 1966	Australia, Tasmania
35	Australian Geodetic 1984	Australia, Tasmania
36	Ayabelle Lighthouse	Djibouti
37	Bellevue (IGN)	Efate and Erromango Islands
38	Bermuda 1957	Bermuda

39	Bissau	Guinea-Bissau
40	Bogota Observatory	Colombia
41	Bukit Rimpah	Indonesia(Bangka and Belitung Ids)
42	Camp Area Astro	Antarctica(McMurdi Camp Area)
43	Campo Inchauspe	Argentina
44	Canton Astro1966	Phoenix Island
45	Cape	South Africa
46	Cape Canaveral	Bahamas, Florida
47	Carthage	Tunisia
48	Chatham Island Astro1971	New Zealand(Chatham Island)
49	Chua Astro	Paraguay
50	Corrego Alegre	Brazil
51	Dabola	Guinea
52	Deception Island	Deception Island, Antarctica
53	Djakarta (Batavia)	Indonesia(Sumatra)
54	Dos 1968	New Georgia Islands (Gizo Island)
55	Easter Island 1967	Easter Island
56	Estonia Coordinate System1937	Estonia
57	European 1950	Cyprus
58	European 1950	Egypt
59	European 1950	England, Channel Islands, Scotland, Shetland Islands
60	European 1950	England, Ireland, Scotland, Shetland Islands
61	European 1950	Finland, Norway
62	European 1950	Greece
63	European 1950	Iran
64	European 1950	Italy (Sardinia)
65	European 1950	Italy (Sicily)
66	European 1950	Malta
67	European 1950	Mean For Austria, Belgium,Denmark, Finland, France, W Germany, Gibraltar,

		Greece, Italy, Luxembourg, Netherlands, Norway, Portugal, Spain, Sweden, Switzerland
68	European 1950	Mean For Austria, Denmark, France, W Germany, Netherland, Switzerland
69	European 1950	Mean For Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria
70	European 1950	Portugal, Spain
71	European 1950	Tunisia,
72	European 1979	Mean For Austria, Finland, Netherlands, Norway, Spain, Sweden, Switzerland
73	Fort Thomas 1955	Nevis St Kitts (Leeward Islands)
74	Gan 1970	Republic Of Maldives
75	Geodetic Datum 1970	New Zealand
76	Graciosa Base SW1948	Azores (Faial, Graciosa, Pico, Sao, Jorge, Terceira)
77	Guam 1963	Guam
78	Gunung Segara	Indonesia (Kalimantan)
79	Gux 1 Astro	Guadalcanal Island
80	Herat North	Afghanistan
81	Hermannskogel Datum	Croatia-Serbia, Bosnia-Herzegovina
82	Hjorsey 1955	Iceland
83	Hongkong 1963	Hongkong
84	Hu Tzu Shan	Taiwan
85	Indian	Bangladesh
86	Indian	India, Nepal
87	Indian	Pakistan
88	Indian 1954	Thailand
89	Indian 1960	Vietnam (Con Son Island)
90	Indian 1960	Vietnam (Near 16 deg N)
91	Indian 1975	Thailand
92	Indonesian 1974	Indonesian
93	Ireland 1965	Ireland

94	ISTS 061 Astro 1968	South Georgia Islands
95	ISTS 073 Astro 1969	Diego Garcia
96	Johnston Island 1961	Johnston Island
97	Kandawala	Sri Lanka
98	Kerguelen Island 1949	Kerguelen Island
99	Kertau 1948	West Malaysia and Singapore
100	Kusaie Astro 1951	Caroline Islands
101	Korean Geodetic System	South Korea
102	LC5 Astro 1961	Cayman Brac Island
103	Leigon	Ghana
104	Liberia 1964	Liberia
105	Luzon	Philippines (Excluding Mindanao)
106	Luzon	Philippines (Mindanao)
107	M'Poraloko	Gabon
108	Mahe 1971	Mahe Island
109	Massawa	Ethiopia (Eritrea)
110	Merchich	Morocco
111	Midway Astro 1961	Midway Islands
112	Minna	Cameroon
113	Minna	Nigeria
114	Montserrat Island Astro 1958	Montserrat (Leeward Island)
115	Nahrwan	Oman (Masirah Island)
116	Nahrwan	Saudi Arabia
117	Nahrwan	United Arab Emirates
118	Naparima BWI	Trinidad and Tobago
119	North American 1927	Alaska (Excluding Aleutian Ids)
120	North American 1927	Alaska (Aleutian Ids East of 180 degW)
121	North American 1927	Alaska (Aleutian Ids West of 180 degW)

122	North American 1927	Bahamas (Except San Salvador Islands)
123	North American 1927	Bahamas (San Salvador Islands)
124	North American 1927	Canada (Alberta, British Columbia)
125	North American 1927	Canada (Manitoba, Ontario)
126	North American 1927	Canada (New Brunswick, Newfoundland, Nova Scotia, Qubec)
127	North American 1927	Canada (Northwest Territories, Saskatchewan)
128	North American 1927	Canada (Yukon)
129	North American 1927	Canal Zone
130	North American 1927	Cuba
131	North American 1927	Greenland (Hayes Peninsula)
132	North American 1927	Mean For Antigua, Barbados, Barbuda, Caicos Islands, Cuba, Dominican, Grand Cayman, Jamaica, Turks Islands
133	North American 1927	Mean For Belize, Costa Rica, El Salvador, Guatemala, Honduras, Nicaragua
134	North American 1927	Mean For Canada
135	North American 1927	Mean For Conus
136	North American 1927	Mean For Conus (East of Mississippi, River Including Louisiana, Missouri, Minnesota)
137	North American 1927	Mean For Conus (West of Mississippi, Rive Excluding Louisiana, Minnesota, Missouri)
138	North American 1927	Mexico
139	North American 1983	Alaska (Excluding Aleutian Ids)
140	North American 1983	Aleutian Ids
141	North American 1983	Canada
142	North American 1983	Conus
143	North American 1983	Hahawii
144	North American 1983	Mexico, Central America
145	North Sahara 1959	Algeria
146	Observatorio Meteorologico 1939	Azores (Corvo and Flores Islands)
147	Old Egyptian 1907	Egypt
148	Old Hawaiian	Hawaii

149	Old Hawaiian	Kauai
150	Old Hawaiian	Maui
151	Old Hawaiian	Mean For Hawaii, Kauai, Maui, Oahu
152	Old Hawaiian	Oahu
153	Oman	Oman
154	Ordnance Survey Great Britian 1936	England
155	Ordnance Survey Great Britian 1936	England, Isle of Man, Wales
156	Ordnance Survey Great Britian 1936	Mean For England ,Isle of Man, Scotland, Shetland Island, Wales
157	Ordnance Survey Great Britian 1936	Scotland, Shetland Islands
158	Ordnance Survey Great Britian 1936	Wales
159	Pico de las Nieves	Canary Islands
160	Pitcairn Astro 1967	Pitcairn Island
161	Point 58	Mean For Burkina Faso and Niger
162	Pointe Noire 1948	Congo
163	Porto Santo 1936	Porto Santo, Maderia Islands
164	Provisional South American 1956	Bolovia
165	Provisional South American 1956	Chile (Northern Near 19 deg S)
166	Provisional South American 1956	Chile (Southern Near 43 deg S)
167	Provisional South American 1956	Colombia
168	Provisional South American 1956	Ecuador
169	Provisional South American 1956	Guyana
170	Provisional South	Mean For Bolivia Chile,Colombia, Ecuador, Guyana, Peru, Venezuela



	American 1956	
171	Provisional South American 1956	Peru
172	Provisional South American 1956	Venezuela
173	Provisional South Chilean 1963	Chile (Near 53 deg S) (Hito XVIII)
174	Puerto Rico	Puerto Rico, Virgin Islands
175	Pulkovo 1942	Russia
176	Qatar National	Qatar
177	Qornoq	Greenland (South)
178	Reunion	Mascarene Island
179	Rome 1940	Italy (Sardinia)
180	S-42 (Pulkovo 1942)	Hungary
181	S-42 (Pulkovo 1942)	Poland
182	S-42 (Pulkovo 1942)	Czechoslovakia
183	S-42 (Pulkovo 1942)	Lativa
184	S-42 (Pulkovo 1942)	Kazakhstan
185	S-42 (Pulkovo 1942)	Albania
186	S-42 (Pulkovo 1942)	Romania
187	S-JTSK	Czechoslovakia (Prior 1 Jan1993)
188	Santo (Dos) 1965	Espirito Santo Island
189	Sao Braz	Azores (Sao Miguel, Santa Maria Ids)
190	Sapper Hill 1943	East Falkland Island
191	Schwarzeck	Namibia
192	Selvagem Grande 1938	Salvage Islands
193	Sierra Leone 1960	Sierra Leone
194	South American 1969	Argentina
195	South American 1969	Bolivia
196	South American 1969	Brazil

197	South American 1969	Chile
198	South American 1969	Colombia
199	South American 1969	Ecuador
200	South American 1969	Ecuador (Baltra, Galapagos)
201	South American 1969	Guyana
202	South American 1969	Mean For Argentina, Bolivia, Brazil, Chile, Colombia, Ecuador, Guyana, Paraguay, Peru, Trinidad and Tobago, Venezuela
203	South American 1969	Paraguay
204	South American 1969	Peru
205	South American 1969	Trinidad and Tobago
206	South American 1969	Venezuela
207	South Asia	Singapore
208	Tananarive Observatory 1925	Madagascar
209	Timbalai 1948	Brunei, E Malaysia (Sabah Sarawak)
210	Tokyo	Japan
211	Tokyo	Mean For Japan, South Korea, Okinawa
212	Tokyo	Okinawa
213	Tokyo	South Korea
214	Tristan Astro 1968	Tristan Da Cunha
215	Viti Levu 1916	Fiji (Viti Levu Island)
216	Voirol 1960	Algeria
217	Wake Island Astro 1952	Wake Atoll
218	Wake-Eniwetok 1960	Marshall Islands
219	WGS 1972	Global Definition
220	WGS 1984	Global Definition
221	Yacare	Uruguay
222	Zanderij	Suriname
223	PZ-90 v11	GLONASS

## Document change list

### Revision 1.0

- Initial version released on May 27, 2024.

### Revision 1.1 (October 18, 2024)

- Added the command ID 162, 163, 442, 443, 496, 498, 507, 508, 509, 510, 511, 512, 753, 755, 756, 757, 758, 763.
- Removed the command ID 490, 491, 493.